## Taylor's Formula

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There's a lot more to be said about Taylor's formula than the brief discussion on pp.113-4 of Apostol. Let me begin with a few definitions.

Definitions. A function $f$ defined on an interval $I$ is called $k$ times differentiable on $I$ if the derivatives $f^{\prime}, f^{\prime \prime}, \ldots, f^{(k)}$ exist and are finite on $I$, and $f$ is said to be of class $C^{k}$ on $I$ if these derivatives are all continuous on $I$. (Note that if $f$ is $k$ times differentiable, the derivatives $f^{\prime}, \ldots, f^{(k-1)}$ are necessarily continuous, by Theorem 5.3 ; the only question is the continuity of $f^{(k)}$.) If $f$ is (at least) $k$ times differentiable on an open interval $I$ and $c \in I$, its $k$ th order Taylor polynomial about $c$ is the polynomial

$$
P_{k, c}(x)=\sum_{j=0}^{k} \frac{f^{(j)}(c)}{j!}(x-c)^{j}
$$

(where, of course, the "zeroth derivative" $f^{(0)}$ is $f$ itself), and its $k$ th order Taylor remainder is the difference

$$
R_{k, c}(x)=f(x)-P_{k, c}(x)
$$

Remark 1. The $k$ th order Taylor polynomial $P_{k, c}(x)$ is a polynomial of degree at most $k$, but its degree may be less than $k$ because $f^{(k)}(c)$ might be zero.

Remark 2. We have $P_{k, c}(c)=f(c)$, and by differentiating the formula for $P_{k, c}(x)$ repeatedly and then setting $x=c$ we see that $P_{k, c}^{(j)}(c)=f^{(j)}(c)$ for $j \leq k$. That is, $P_{k, c}$ is the polynomial of degree $\leq k$ whose whose derivatives of order $\leq k$ at $c$ agree with those of $f$.

For future reference, here are a few frequently used examples of Taylor polynomials:

$$
\begin{aligned}
f(x)=e^{x} ; & P_{k, 0}(x)=\sum_{0 \leq j \leq k} \frac{x^{j}}{j!} \\
f(x)=\cos x ; & P_{k, 0}(x)=\sum_{0 \leq j \leq k / 2} \frac{(-1)^{j} x^{2 j}}{(2 j)!} \\
f(x)=\sin x ; & P_{k, 0}(x)=\sum_{0 \leq j<k / 2} \frac{(-1)^{j} x^{2 j+1}}{(2 j+1)!} \\
f(x)=\log x ; & P_{k, 1}(x)=\sum_{1 \leq j \leq k} \frac{(-1)^{j-1}(x-1)^{j}}{j}
\end{aligned}
$$

Note that (for example) $1-\frac{1}{2} x^{2}$ is both the 2 nd order and the 3 rd order Taylor polynomial of $\cos x$, because the cubic term in its Taylor expansion vanishes. (Also note that in higher mathematics the natural logarithm function is almost always called $\log$ rather than $\ln$.)

For $k=1$ we have $P_{1, c}(x)=f(c)+f^{\prime}(c)(x-c)$; this is the linear function whose graph is the tangent line to the graph of $f$ at $x=c$. Just as this tangent line is the straight line
that best approximates the graph of $f$ near $x=c$, we shall see that $P_{k, c}(x)$ is the polynomial of degree $\leq k$ that best approximates $f(x)$ near $x=c$. To justify this assertion we need to see that the remainder $R_{k, c}(x)$ is suitably small near $x=c$, and there are several ways of making this precise. The first one is simply this: the remainder $R_{k, c}(x)$ tends to zero as $x \rightarrow c$ faster than any nonzero term in the polynomial $P_{k, c}(x)$, that is, faster than $(x-c)^{k}$. Here is the result:

Theorem 1. Suppose $f$ is $k$ times differentiable in an open interval I containing the point c. Then

$$
\lim _{x \rightarrow c} \frac{R_{k, c}(x)}{(x-c)^{k}}=\lim _{x \rightarrow c} \frac{f(x)-P_{k, c}(x)}{(x-c)^{k}}=0
$$

Proof. Since $f$ and its derivatives up to order $k$ agree with $P_{k, c}$ and its derivatives up to order $k$ at $x=c$, the difference $R_{k, c}$ and its derivatives up to order $k$ vanish at $x=c$. Moreover, $(x-c)^{k}$ and its derivatives up to order $k-1$ also vanish at $x=c$, so we can apply l'Hôpital's rule $k$ times to obtain

$$
\lim _{x \rightarrow c} \frac{R_{k, c}(x)}{(x-c)^{k}}=\lim _{x \rightarrow c} \frac{R_{k, c}^{(k)}(x)}{k(k-1) \cdots 1(x-c)^{0}}=\frac{0}{k!}=0 .
$$

There is a convenient notation to describe the situation in Theorem 1: we say that

$$
R_{k, c}(x)=o\left((x-c)^{k}\right) \text { as } x \rightarrow c,
$$

meaning that $R_{k, c}(x)$ is of smaller order than $(x-c)^{k}$ as $x \rightarrow c$. More generally, if $g$ and $h$ are two functions, we say that $h(x)=o(g(x))$ as $x \rightarrow c$ (where $c$ might be $\pm \infty$ ) if $h(x) / g(x) \rightarrow 0$ as $x \rightarrow c$. The symbol $o(g(x))$ is pronounced "little oh of $g$ of $x$ "; it does not denote any particular function, but rather is a shorthand way of describing any function that is of smaller order than $g(x)$ as $x \rightarrow c$. For example, Corollary 1 of l'Hôpital's rule (see the notes on l'Hôpital's rule) says that for any $a>0, x^{a}=o\left(e^{x}\right)$ and $\log x=o\left(x^{a}\right)$ as $x \rightarrow \infty$, and $\log x=o\left(x^{-a}\right)$ as $x \rightarrow 0+$. Another example: saying that $h(x)=o(1)$ as $x \rightarrow c$ simply means that $\lim _{x \rightarrow c} h(x)=0$.

In order to simplify notation, in the following discussion we shall assume that $c=0$ and write $P_{k}$ instead of $P_{k, c}$. (The Taylor polynomial $P_{k}=P_{k, 0}$ is often called the $k$ th order Maclaurin polynomial of $f$.) There is no loss of generality in doing this, as one can always reduce to the case $c=0$ by making the change of variable $\widetilde{x}=x-c$ and regarding all functions in question as functions of $\widetilde{x}$ rather than $x$.

The conclusion of Theorem 1 , that $f(x)-P_{k}(x)=o\left(x^{k}\right)$, actually characterizes the Taylor polynomial $P_{k, c}$ completely:

Theorem 2. Suppose $f$ is $k$ times differentiable on an open interval I containing 0. If $Q$ is a polynomial of degree $\leq k$ such that $f(x)-Q(x)=o\left(x^{k}\right)$ as $x \rightarrow 0$, then $Q=P_{k}$.

Proof. Since $f-Q$ and $f-P_{k}$ are both of smaller order than $x^{k}$, so is their difference $P_{k}-Q$. Let $P_{k}(x)=\sum_{0}^{k} a_{j} x^{j}$ (of course $a_{j}=f^{(j)}(0) / j!$ ) and $Q(x)=\sum_{0}^{k} b_{j} x^{j}$. Then

$$
\left(a_{0}-b_{0}\right)+\left(a_{1}-b_{1}\right) x+\cdots+\left(a_{k}-b_{k}\right) x^{k}=P_{k}(x)-Q(x)=o\left(x^{k}\right)
$$

Letting $x \rightarrow 0$, we see that $a_{0}-b_{0}=0$. This being the case, we have

$$
\left(a_{1}-b_{1}\right)+\left(a_{2}-b_{2}\right) x+\cdots+\left(a_{k}-b_{k}\right) x^{k-1}=\frac{P_{k}(x)-Q(x)}{x}=o\left(x^{k-1}\right)
$$

Letting $x \rightarrow 0$ here, we see that $a_{1}-b_{1}=0$. But then

$$
\left(a_{2}-b_{2}\right)+\left(a_{3}-b_{3}\right) x+\cdots+\left(a_{k}-b_{k}\right) x^{k-2}=\frac{P_{k}(x)-Q(x)}{x^{2}}=o\left(x^{k-2}\right)
$$

which likewise gives $a_{2}-b_{2}=0$. Proceeding inductively, we find that $a_{j}=b_{j}$ for all $j$ and hence $P_{k}=Q$.

Theorem 2 is very useful for calculating Taylor polynomials. It shows that using the formula $a_{k}=f^{(k)}(0) / k$ ! is not the only way to calculate $P_{k}$; rather, if by any means we can find a polynomial $Q$ of degree $\leq k$ such that $f(x)=Q(x)+o\left(x^{k}\right)$, then $Q$ must be $P_{k}$. Here are two important applications of this fact.

Taylor Polynomials of Products. Let $P_{k}^{f}$ and $P_{k}^{g}$ be the $k$ th order Taylor polynomials of $f$ and $g$, respectively. Then

$$
\begin{aligned}
f(x) g(x) & =\left[P_{k}^{f}(x)+o\left(x^{k}\right)\right]\left[P_{k}^{g}(x)+o\left(x^{k}\right)\right] \\
& =\left[\text { terms of degree } \leq k \text { in } P_{k}^{f}(x) P_{k}^{g}(x)\right]+o\left(x^{k}\right) .
\end{aligned}
$$

Thus, to find the $k$ th order Taylor polynomial of $f g$, simply multiply the $k$ th Taylor polynomials of $f$ and $g$ together, discarding all terms of degree $>k$.

Example 1. What is the 6 th order Taylor polynomial of $x^{3} e^{x}$ ? Solution:

$$
x^{3} e^{x}=x^{3}\left[1+x+\frac{x^{2}}{2}+\frac{x^{3}}{6}+o\left(x^{3}\right)\right]=x^{3}+x^{4}+\frac{x^{5}}{2}+\frac{x^{6}}{6}+o\left(x^{6}\right)
$$

so the answer is $x^{3}+x^{4}+\frac{1}{2} x^{5}+\frac{1}{6} x^{6}$.
Example 2 What is the 5 th order Taylor polynomial of $e^{x} \sin 2 x$ ? Solution:

$$
\begin{aligned}
e^{x} \sin 2 x & =\left[1+x+\frac{x^{2}}{2}+\frac{x^{3}}{6}+\frac{x^{4}}{24}+\frac{x^{5}}{120}+o\left(x^{5}\right)\right]\left[2 x-\frac{(2 x)^{3}}{6}+\frac{(2 x)^{5}}{120}+o\left(x^{5}\right)\right] \\
& =2 x+2 x^{2}+x^{3}\left[\frac{2}{2}-\frac{8}{6}\right]+x^{4}\left[\frac{2}{6}-\frac{8}{6}\right]+x^{5}\left[\frac{2}{24}-\frac{8}{12}+\frac{32}{120}\right]+o\left(x^{5}\right),
\end{aligned}
$$

so the answer is $2 x+2 x^{2}-\frac{1}{3} x^{3}-x^{4}-\frac{19}{60} x^{5}$.

Taylor Polynomials of Compositions. If $f$ and $g$ have derivatives up to order $k$, and $g(0)=0$, we can find the $k$ th Taylor polynomial of $f \circ g$ by substituting the Taylor expansion of $g$ into the Taylor expansion of $f$, retaining only the terms of degree $\leq k$. That is, suppose

$$
f(x)=a_{0}+a_{1} x+\cdots+a_{k} x^{k}+o\left(x^{k}\right)
$$

Since $g(0)=0$ and $g$ is differentiable, we have $g(x) \approx g^{\prime}(0) x$ for $x$ near 0 , so anything that is $o\left(g(x)^{k}\right)$ is also $o\left(x^{k}\right)$ as $x \rightarrow 0$. Hence,

$$
f(g(x))=a_{0}+a_{1} g(x)+\cdots+a_{k} g(x)^{k}+o\left(x^{k}\right)
$$

Now plug in the Taylor expansion of $g$ on the right and multiply it out, discarding terms of degree $>k$.

Example 3. What is the 16 th order Taylor polynomial of $e^{x^{6}}$ ? Solution:

$$
e^{x}=1+x+\frac{x^{2}}{2}+\frac{x^{3}}{6}+o\left(x^{3}\right) \quad \Longrightarrow \quad e^{x^{6}}=1+x^{6}+\frac{x^{12}}{2}+\frac{x^{18}}{6}+o\left(x^{18}\right)
$$

The last two terms are both $o\left(x^{16}\right)$, so the answer is $1+x^{6}+\frac{1}{2} x^{12}$.
Example 4. What is the 4th order Taylor polynomial of $e^{\sin x}$ ? Solution:

$$
e^{\sin x}=1+\sin x+\frac{\sin ^{2} x}{2}+\frac{\sin ^{3} x}{6}+\frac{\sin ^{4} x}{24}+o\left(x^{4}\right)
$$

since $|\sin x| \leq|x|$. Now substitute $x-\frac{1}{6} x^{3}+o\left(x^{4}\right)$ for $\sin x$ on the right (yes, the error term is $o\left(x^{4}\right)$ because the 4th degree term in the Taylor expansion of $\sin x$ vanishes) and multiply out, throwing all terms of degree $>4$ into the " $o\left(x^{4}\right)$ " trash can:

$$
e^{\sin x}=1+\left[x-\frac{x^{3}}{6}\right]+\frac{1}{2}\left[x^{2}-\frac{x^{4}}{3}\right]+\frac{x^{3}}{6}+\frac{x^{4}}{24}+o\left(x^{4}\right)
$$

so the answer is $1+x+\frac{1}{2} x^{2}-\frac{1}{8} x^{4}$. (To appreciate how easy this is, try finding this polynomial by computing the first four derivatives of $e^{\sin x}$.)

Taylor Polynomials and l'Hôpital's Rule. Taylor polynomials can often be used effectively in computing limits of the form $0 / 0$. Indeed, suppose $f, g$, and their first $k-1$ derivatives vanish at $x=0$, but their $k$ th derivatives do not both vanish. The Taylor expansions of $f$ and $g$ then look like

$$
f(x)=\frac{f^{(k)}(0)}{k!} x^{k}+o\left(x^{k}\right), \quad g(x)=\frac{g^{(k)}(0)}{k!} x^{k}+o\left(x^{k}\right) .
$$

Taking the quotient and cancelling out $x^{k} / k!$, we get

$$
\frac{f(x)}{g(x)}=\frac{f^{(k)}(0)+o(1)}{g^{(k)}(0)+o(1)} \rightarrow \frac{f^{(k)}(0)}{g^{(k)}(0)} \text { as } x \rightarrow 0
$$

This is in accordance with l'Hôpital's rule, but the devices discussed above for computing Taylor polynomials may lead to the answer more quickly than a direct application of l'Hôpital.

Example 5. What is $\lim _{x \rightarrow 0}\left(x^{2}-\sin ^{2} x\right) / x^{2} \sin ^{2} x$ ? Solution:

$$
\sin ^{2} x=\left[x-\frac{x^{3}}{6}+o\left(x^{4}\right)\right]^{2}=x^{2}-\frac{x^{4}}{3}+o\left(x^{4}\right)
$$

so $x^{2} \sin ^{2} x=x^{4}+o\left(x^{4}\right)$, and

$$
\frac{x^{2}-\sin ^{2} x}{x^{2} \sin ^{2} x}=\frac{\frac{1}{3} x^{4}+o\left(x^{4}\right)}{x^{4}+o\left(x^{4}\right)}=\frac{\frac{1}{3}+o(1)}{1+o(1))} \rightarrow \frac{1}{3} .
$$

(Again, to appreciate how easy this is, try doing it by l'Hôpital's rule.)
Example 6. Evaluate

$$
\lim _{x \rightarrow 1}\left[\frac{1}{\log x}+\frac{x}{x-1}\right]
$$

Solution: Here we need to expand in powers of $x-1$. First of all,

$$
\frac{1}{\log x}-\frac{x}{x-1}=\frac{x-1-x \log x}{(x-1) \log x}=\frac{(x-1)-(x-1) \log x-\log x}{(x-1) \log x} .
$$

Next, $\log x=(x-1)-\frac{1}{2}(x-1)^{2}+o\left((x-1)^{2}\right)$, and plugging this into the numerator and denominator gives

$$
\frac{(x-1)-(x-1)^{2}-\left[(x-1)-\frac{1}{2}(x-1)^{2}\right]+o\left((x-1)^{2}\right)}{(x-1)^{2}+o\left((x-1)^{2}\right)}=\frac{-\frac{1}{2}+o(1)}{1+o(1)} \rightarrow-\frac{1}{2} .
$$

Theorem 1 tells us a lot about the remainder $R_{k, c}(x)=f(x)-P_{k, c}(x)$ for small $x$, but sometimes one wants a more precise quantitative estimate of it. The most common ways of obtaining such an estimate involve slightly stronger conditions on $f$; namely, instead of just being $k$ times differentiable we assume that it is $k+1$ times differentiable, or perhaps of class $C^{k+1}$, and the estimates we obtain involve bounds on the derivative $f^{(k+1)}$. There are several formulas for $R_{k, c}(x)$ that lead to such estimates; we shall present the two that are most often encountered. The first one is the one presented in Apostol. (It's Theorem 5.19 , with the change of variable $k=n-1$. Apostol states the hypotheses in a slightly more general, but also more complicated, form; the version below usually suffices.)

Theorem 3 (Lagrange's Form of the Remainder). Suppose $f$ is $k+1$ times differentiable on an open interval $I$ and $c \in I$. For each $x \in I$ there is a point $x_{1}$ between $c$ and $x$ such that

$$
\begin{equation*}
R_{k, c}(x)=\frac{f^{(k+1)}\left(x_{1}\right)}{(k+1)!}(x-c)^{k+1} \tag{1}
\end{equation*}
$$

For the proof of Theorem 3 we refer to Apostol. The other popular form of the remainder requires a slightly stronger hypothesis, that $f^{(k+1)}$ not only exists but is continuous. (Actually, it's enough for it to be Riemann integrable, but these minor variations in the assumptions are usually of little importance.) I suspect the reason that Apostol doesn't mention it is that it involves an integral, and he doesn't want to discuss integrals until later.

Theorem 4 (Integral Form of the Remainder). Suppose $f$ is of class $C^{k+1}$ on an open interval $I$ and $c \in I$. If $x \in I$, then

$$
\begin{equation*}
R_{k, c}(x)=\frac{1}{(k+1)!} \int_{c}^{x}(x-t)^{k} f^{(k+1)}(t) d t \tag{2}
\end{equation*}
$$

Proof. Recalling the definition of $R_{k, c}$, we can restate (2) as

$$
\begin{equation*}
f(x)=\sum_{j=0}^{k} \frac{f^{(j)}(c)}{j!}(x-c)^{j}+\frac{1}{(k+1)!} \int_{c}^{x}(x-t)^{k} f^{(k+1)}(t) d t \tag{3}
\end{equation*}
$$

For $k=0$, this simply says that

$$
\begin{equation*}
f(x)=f(c)+\int_{c}^{x} f^{\prime}(t) d t \tag{4}
\end{equation*}
$$

which is true by the fundamental theorem of calculus. Next, we integrate (4) by parts, taking

$$
u=f^{\prime}(t), \quad d u=f^{\prime \prime}(t) d t ; \quad d v=d t, \quad v=t-x
$$

Notice the twist: normally if $d v=d t$ we would simply take $v=t$, but we are free to add a constant of integration, and we take that constant to be $-x$. (The number $x$, like $c$, is fixed in this discussion; the variable of integration is $t$.) The result is

$$
\begin{aligned}
f(x) & =f(c)+\left.(t-x) f^{\prime}(t)\right|_{c} ^{x}-\int_{c}^{x}(t-x) f^{\prime \prime}(t) d t \\
& =f(c)+(x-c) f^{\prime}(c)+\int_{c}^{x}(x-t) f^{\prime \prime}(t) d t
\end{aligned}
$$

which is (3) with $k=1$. Another integration by parts, with

$$
u=f^{\prime \prime}(t), \quad d u=f^{\prime \prime \prime}(t) d t ; \quad d v=(x-t) d t, \quad v=-\frac{1}{2}(x-t)^{2}
$$

(again, instead of taking $v=x t-\frac{1}{2} t^{2}$ we take $v=-\frac{1}{2}(x-t)^{2}=-\frac{1}{2} x^{2}+x t-\frac{1}{2} t^{2}$ ) gives

$$
\begin{aligned}
f(x) & =f(c)+(x-c) f^{\prime}(c)-\left.\frac{1}{2}(x-t)^{2} f^{\prime \prime}(t)\right|_{c} ^{x}+\int_{c}^{x} \frac{1}{2}(x-t)^{2} f^{\prime \prime \prime}(t) d t \\
& =f(c)+(x-c) f^{\prime}(c)+\frac{(x-c)^{2}}{2!} f^{\prime \prime}(c)+\frac{1}{2!} \int_{c}^{x}(x-t)^{2} f^{\prime \prime \prime}(t) d t
\end{aligned}
$$

which is (3) with $k=2$. The pattern should now be clear: a $k$-fold integration by parts starting from (4) yields (3). The formal inductive proof is left to the reader.

Let's be clear about the significance of Theorems 3 and 4. They are almost never used to find the exact value of the remainder term (which amounts to knowing the exact value of the original $f(x)$ ); one doesn't know just where the point $x_{1}$ in (1) is, and the integral in
(2) is usually hard to evaluate. Instead, the philosophy is that Taylor polynomials $P_{k, c}$ are used as (simpler) approximations to (complicated) functions $f$ near $c$, and the remainders $R_{k, c}$ are regarded as junk to be disregarded. For this to work one needs some assurance that $R_{k, c}(x)$ is small enough that one can safely neglect it or an estimate of the magnitude of the error one makes in doing so. The main purpose of Theorems 3 and 4 is to provide such information via the following result.
Corollary 1. Suppose $f$ is $k+1$ times differentiable on an interval I and that $\left|f^{(k+1)}(x)\right| \leq C$ for $x \in I$. Then for any $x, c \in I$ we have

$$
\begin{equation*}
\left|R_{k, c}(x)\right| \leq C \frac{|x-c|^{k+1}}{(k+1)!} \tag{5}
\end{equation*}
$$

Proof. The estimate (5) is clearly an immediate consequence of (1). It also follows easily from (2): if $x>c$,

$$
\left|R_{k, c}(x)\right| \leq \frac{C}{k!} \int_{c}^{x}(x-t)^{k} d t=-\left.\frac{C}{k!} \frac{(x-t)^{k+1}}{k+1}\right|_{c} ^{x}=C \frac{(x-c)^{k+1}}{(k+1)!}
$$

and if $x<c$,

$$
\left|R_{k, c}(x)\right| \leq \frac{C}{k!}\left|\int_{c}^{x}(x-t)^{k} d t\right|=\frac{C}{k!} \int_{x}^{c}(t-x)^{k} d t=\frac{C}{k!} \frac{(c-x)^{k+1}}{k+1}=C \frac{|x-c|^{k+1}}{(k+1)!} .
$$

Observe that Corollary 1 is a more precise and quantitative version of Theorem 1 (under slightly stronger hypotheses on $f$ ): Theorem 1 says that $R_{k, c}(x)$ vanishes faster than $(x-c)^{k}$ as $x \rightarrow c$; Corollary 1 says that it vanishes at least at a rate proportional to $(x-c)^{k+1}$ and gives a good estimate for the proportionality constant. The best estimate is obtained by taking $C$ to be the least upper bound for $\left|f^{(k+1)}\right|$ on $I$, but it is usually not crucial to compute this optimal value for $C$. What is crucial, however, and what some people find easy to forget, is the use of absolute values. It's the size of $R_{k, c}(x)$ that matters.

A typical use of Taylor polynomials is to evaluate integrals of functions that don't have an elementary antiderivative. Here's an example.

Example 7. The function $f(x)=e^{-x^{2}}$ has no elementary antiderivative. However, we can do a Taylor approximation of $e^{-x^{2}}$ and integrate the resulting polynomial. The efficient way to proceed is to consider the Taylor approximations of $e^{-y}$ (easier to compute with!) and then set $y=x^{2}$. Since $\left|(d / d y)^{j} e^{-y}\right|=\left|(-1)^{j} e^{-y}\right| \leq 1$ for $y \geq 0$, the estimate (5) shows that

$$
e^{-y}=1-y+\frac{y^{2}}{2}-\cdots+(-1)^{k} \frac{y^{k}}{k!}+R_{k, 0}(y), \text { where }\left|R_{k, 0}(y)\right| \leq \frac{y^{k+1}}{(k+1)!} \text { for } y \geq 0
$$

Setting $y=x^{2}$ yields

$$
e^{-x^{2}}=1-x^{2}+\frac{x^{4}}{2!}-\cdots+(-1)^{k} \frac{x^{2 k}}{k!}+R_{k, 0}\left(x^{2}\right), \text { where }\left|R_{k, 0}\left(x^{2}\right)\right| \leq \frac{x^{2 k+2}}{(k+1)!}
$$

Therefore,

$$
\int_{0}^{x} e^{-t^{2}} d t=x-\frac{x^{3}}{3}+\frac{x^{5}}{5 \cdot 2!}-\cdots+(-1)^{k} \frac{x^{2 k+1}}{(2 k+1) \cdot k!}+\text { error }
$$

where

$$
\mid \text { error }\left|\leq\left|\int_{0}^{x} \frac{t^{2 k+2}}{(k+1)!} d t\right|=\frac{|x|^{2 k+3}}{(2 k+3) \cdot(k+1)!}\right.
$$

For instance, if $x=1$, we can take $k=4$ and obtain

$$
\int_{0}^{1} e^{-t^{2}} d t=1-\frac{1}{3}+\frac{1}{5 \cdot 2}-\frac{1}{7 \cdot 3!}+\frac{1}{9 \cdot 4!}=0.7382 \text { with error less than } 0.0008
$$

A Few Concluding Remarks. Although Theorems 3 and 4 are most commonly used through Corollary 1, there are other things that can be done with them. There's a nice application of Theorem 3 on p. 376 of Apostol, which we'll discuss toward the end of the quarter. For an extra twist on Theorem 4 that yields more estimates, as well as a sharper form of Theorem 1, see my paper "Remainder estimates in Taylor's theorem," American Mathematical Monthly 97 (1990), 233-235 (available online through the UW Libraries site).

