



Towards Exponential Semi-Lagrangian Parallel-in-Time Methods for the Shallow Water Equations on the Rotating Sphere

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Full Outline

- Introduction
- Coarse time stepping methods
- MGRIT
- Numerical tests

Outline

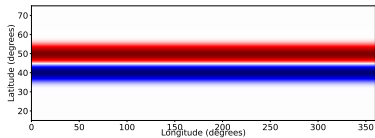
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PinT in atmospheric modelling

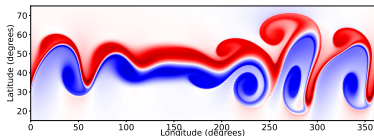
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- Hyperbolic nature, small-scale spatial features;
- Improve stability and convergence
- Choice of coarse time stepping method?

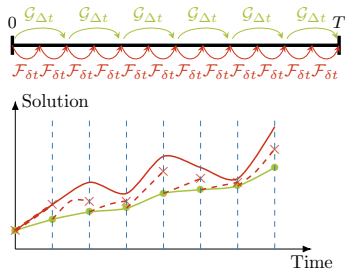
Vorticity field at $t = 0$



Vorticity field at $t = 144h$



[Galewsky, Scott, and Polvani (2004)]



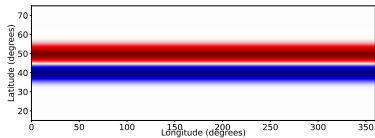
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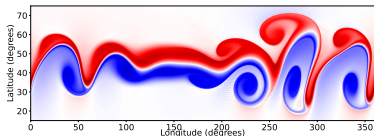
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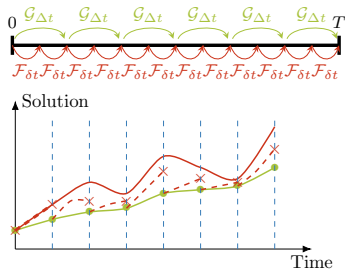
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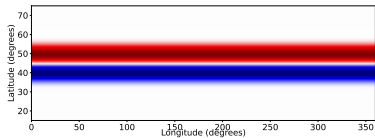
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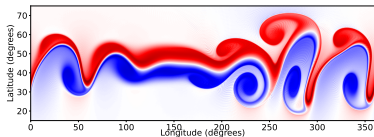
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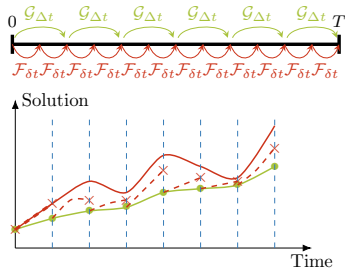
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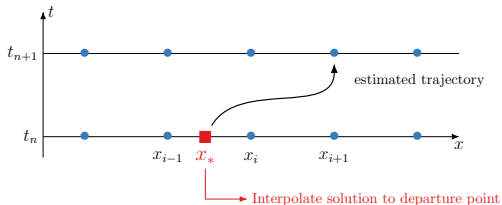
Some possibilities of coarse time stepping method

- Implicit-explicit (IMEX)

$$U^{n+1} = F_I^{\Delta t/2} \left(F_E^{\Delta t} \left(F_I^{\Delta t/2} (U^n) \right) \right)$$

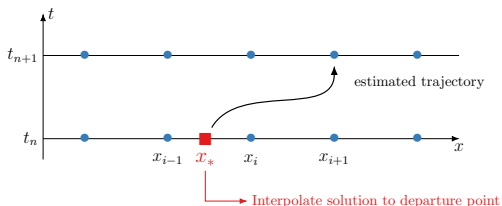
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 - Operational application (e.g. SL-SI-SETTLS in IFS-ECMWF[Hortal (2002)])
 - Application in PinT [Schmitt et al. (2018), De Sterck et al. (2021)]



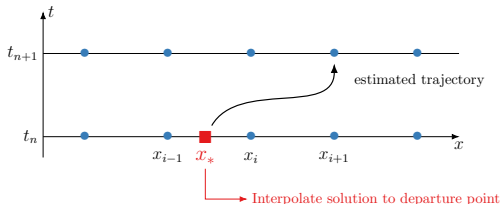
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- Exponential integration methods
 - Exact integration of linear terms
 - e.g. ETD2RK [Cox and Matthews (2002)]

$$\frac{\partial \mathbf{U}}{\partial t} = \mathbf{L}\mathbf{U} + \mathbf{N}(\mathbf{U}) \implies \mathbf{U}^{n+1} = \underbrace{e^{\Delta t \mathbf{L}} \mathbf{U}^n}_{\text{exact}} + \underbrace{e^{\Delta t \mathbf{L}} \int_{t_n}^{t_{n+1}} e^{-(s-t_n)\mathbf{L}} \mathbf{N}(\mathbf{U}(s)) ds}_{\text{approx.}}$$

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- **Semi-Lagrangian exponential integration methods** [Peixoto and Schreiber (2019)]

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Beyond Parareal: Multigrid Reduction in Time (MGRIT)

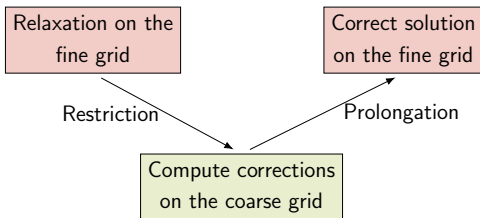
S. Friedhoff et al., "A Multigrid-in-Time Algorithm for Solving Evolution Equations in Parallel", *Presented at: Sixteenth Copper Mountain Conference on Multigrid Methods (2013)*

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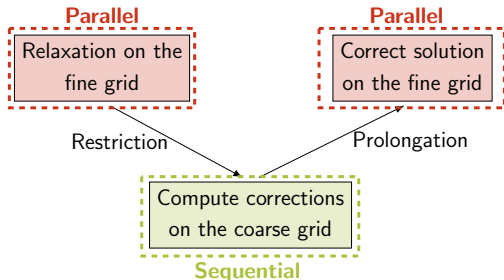
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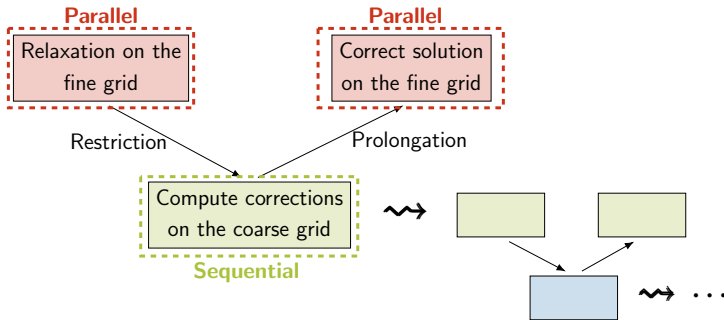
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- Several parameters to be set, e.g. :
 - Number of levels;
 - Coarsening factor between levels: $\Delta t_{l+1} = m\Delta t_l$
 - Relaxation strategy: F, FCF, FCFCF, ..., $F(\text{CF})^{N_{\text{relax}}}$

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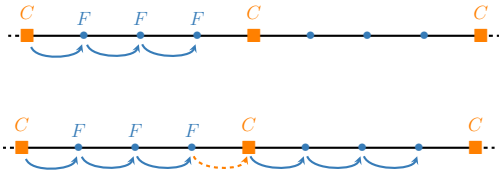
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Stability analysis of MGRIT

- Extension of stability analysis of Parareal [Staff and Rønquist (2005)]

- Linearized ODE: $\frac{\partial u}{\partial t} = \lambda_L u + N(u) \implies \frac{\partial u}{\partial t} = \lambda_L u + \lambda_N u$

- Stability in function of $\xi_N := \lambda_N \Delta t \in \mathbb{C}$ for fixed $\xi_L = \lambda_L \Delta t \in i\mathbb{R}^*$:

$$|A_{\text{scheme}}(\text{Re}(\xi_N), \text{Im}(\xi_N))| \leq 1, \quad u^{n+1} = A_{\text{scheme}} u^n$$

- Stability function of MGRIT (two levels with F(CF)^{N_{relax}}):

$$u_n^k = \underbrace{\left(\sum_{i=0}^{\lfloor k/(N_{\text{relax}}+1) \rfloor} \binom{n - iN_{\text{relax}}}{i} A_f^{mN_{\text{relax}}} (A_f^m - A_c)^i A_c^{n - i(N_{\text{relax}}+1)} \right)}_{A_{\text{MGRIT}}} u_0$$

- Which coarse time stepping scheme?

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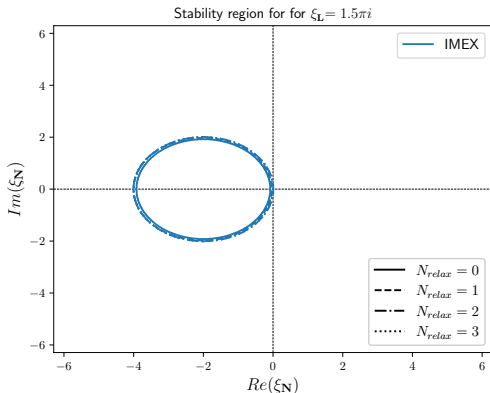
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Which coarse time stepping scheme?

- IMEX
- ETD2RK
- SL-SI-SETTLS
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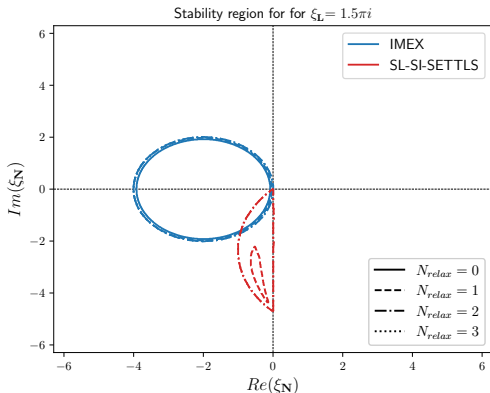
Stability analysis of MGRIT

- Stability in function of the coarse time stepping method and N_{relax}
 - Fine scheme: IMEX
 - Coarse scheme: IMEX , SL-SI-SETTLS , ETD2RK , SL-ETD2RK
 - $k = 2, n = 2, m = 100, \xi_L = \frac{3\pi}{2}i$



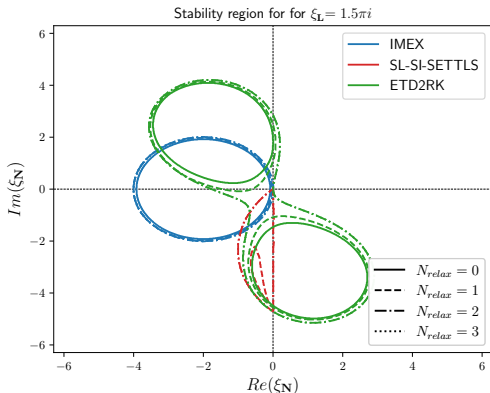
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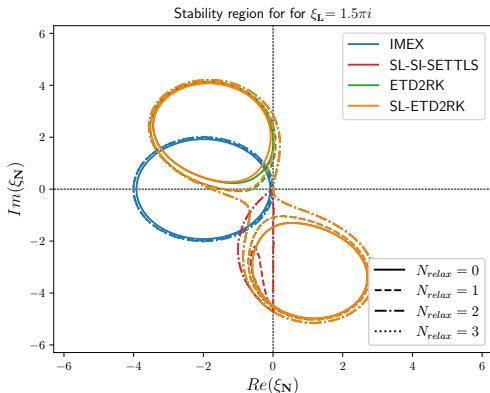
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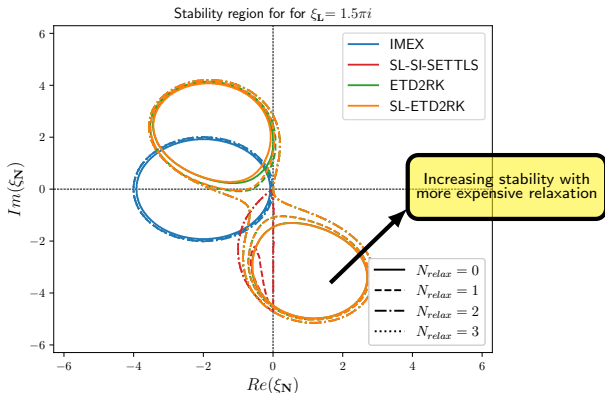
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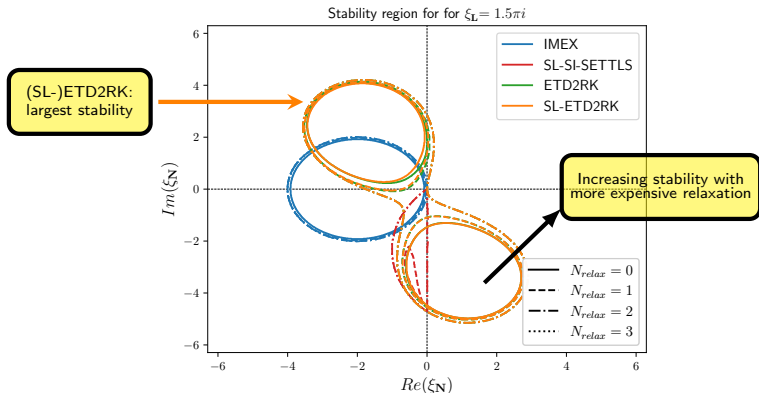
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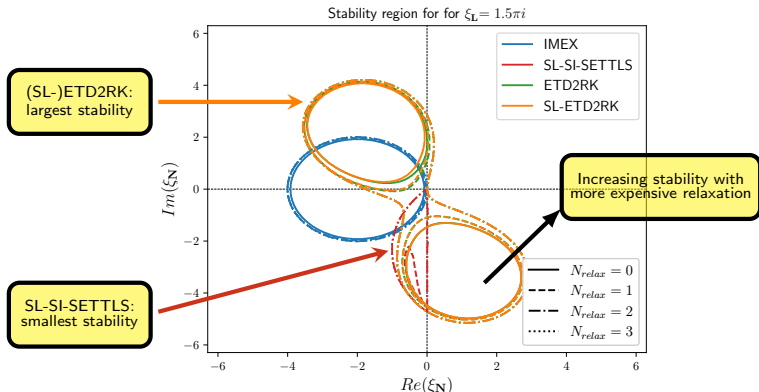
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Test case

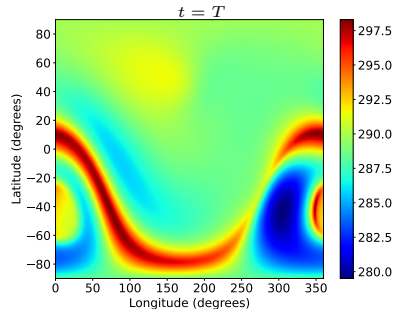
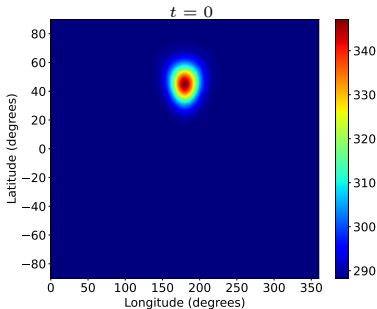
- Shallow water equations on the rotating sphere
- Gaussian bump perturbation in geopotential field Φ
- $T = 102400$
- Reference solution: $\delta t = 60$
- Coarse levels: coarsening factor m
- Artificial diffusion
- Reference solution (geopotential field Φ):

$$\frac{\partial}{\partial t} \mathbf{U} = \mathbf{L}_G \mathbf{U} + \mathbf{L}_C \mathbf{U} + \mathbf{N}_A(\mathbf{U}) + \mathbf{N}_R(\mathbf{U})$$

$$\mathbf{U} = \begin{pmatrix} \Phi \\ \xi \\ \delta \end{pmatrix}, \quad \mathbf{L}_G(\mathbf{U}) = \begin{pmatrix} \bar{\Phi} \delta \\ 0 \\ -\nabla^2 \Phi \end{pmatrix}, \quad \mathbf{L}_C(\mathbf{U}) = \begin{pmatrix} 0 \\ -\nabla \cdot (f\mathbf{V}) \\ -\mathbf{k} \cdot \nabla \times (f\mathbf{V}) \end{pmatrix}$$
$$\mathbf{N}_A(\mathbf{U}) = \begin{pmatrix} -\mathbf{V} \cdot \nabla \Phi \\ -\nabla \cdot (\xi \mathbf{V}) \\ \nabla^2 \left(\frac{\mathbf{V} \cdot \mathbf{V}}{2} \right) + \mathbf{k} \cdot \nabla \times (\xi \mathbf{V}) \end{pmatrix}, \quad \mathbf{N}_R(\mathbf{U}) = \begin{pmatrix} -\Phi' \delta \\ 0 \\ 0 \end{pmatrix}$$

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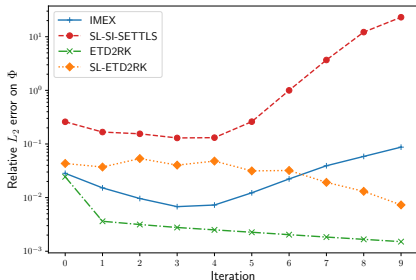
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Errors along iterations in function of the coarse time stepping method:

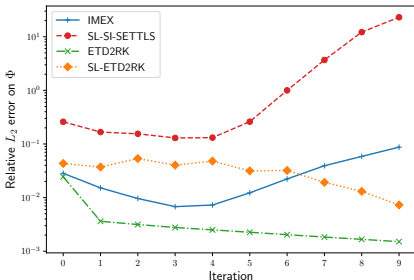
$$N_{\text{levels}} = 2, m = 2, N_{\text{relax}} = 4$$



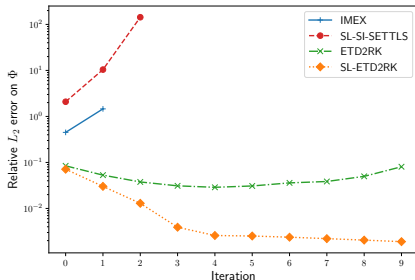
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$$N_{\text{levels}} = 3, m = 4, N_{\text{relax}} = 1$$

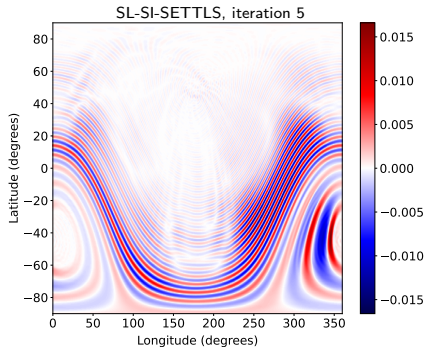
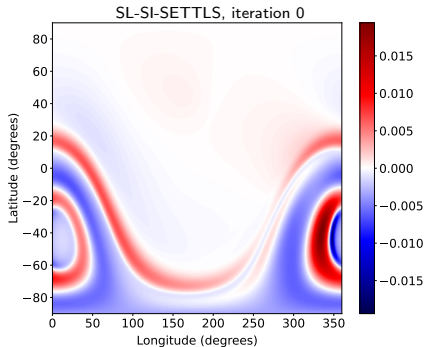


- More levels \implies larger timestep in coarsest level \implies stability issues
- Faster convergence and more stability with exponential methods

Test case

Relative error of geopotential Φ at $t = T$:

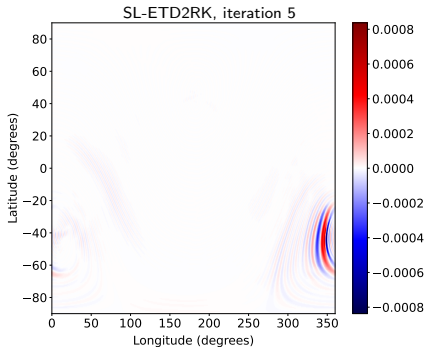
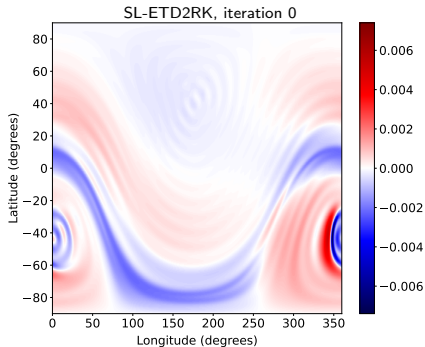
■ Coarse method: SL-SI-SETTLS



Test case

Relative error of geopotential Φ at $t = T$:

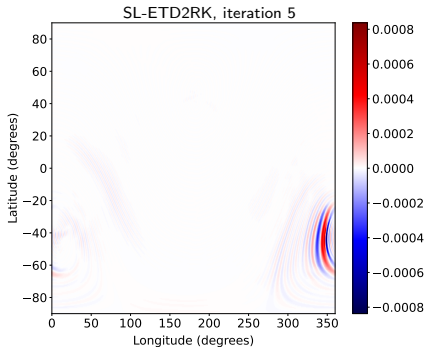
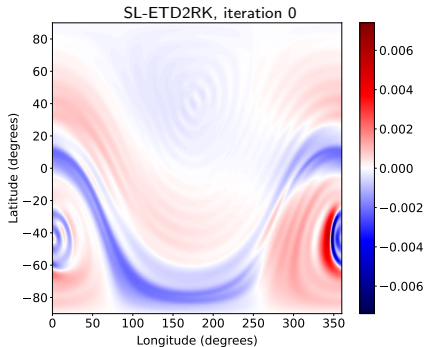
■ Coarse method: SL-ETD2RK



Test case

Relative error of geopotential Φ at $t = T$:

- Coarse method: SL-ETD2RK



- Errors on small-scale spatial features

Conclusions and perspectives

- PinT for the SWE on the rotating sphere, choice of coarse time stepping method
- Poor stability properties using SL-SI-SETTLS in MGRIT
- Improved stability and convergence with ETD2RK and SL-ETD2RK
- Small-scale spatial features are still a bottleneck
- Parallel implementation and study of numerical speedup
- Evaluation of influence of artificial diffusion

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Thank you!

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Outline

- Introduction
- Coarse time stepping methods
- MGRIT
- Numerical tests



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