



# Parallel-in-time methods for fluid dynamics problems

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## **Full Outline**

- Introduction
- Parallel-in-time methods
  - Parareal
  - MGRIT
- Some ideas for improving PinT
- Applications
  - Urban floods
  - Atmospheric circulation models





## Outline

### Introduction

#### • Parallel-in-time methods

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- Accuracy and time-to-solution requirements in several applications
  - Weather forecast and climate modelling
  - Urban floods
  - Real-time forecast and risk assessment





[Guinot, Sanders, and Schubert (2017)]

[ECMWF, windy.com]





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[Hénonin et al. (2013)]





Accuracy and time-to-solution requirements in several applications

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#### Stability limitations

High computational costs

Need for more efficient computational approaches





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- Stagnation of CPUs speed performance gains via parallelism;
- Saturation of spatial parallelism;
- Parallelize the temporal direction?





Stagnation of CPUs speed  $\implies$  performance gains via parallelism;

Saturation of spatial parallelism;

Parallelize the temporal direction?







Stagnation of CPUs speed ⇒ performance gains via parallelism;
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[Schwarz (1870)]







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#### Iterative predictor-corrector algorithms

- Use of fine and coarse timestepping schemes
- Simultaneous computation of several time steps
- Objective: fast convergence to the fine solution





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Jacques-Louis Lions, Yvon Maday, and Gabriel Turinici, "Résolution d'EDP par un schéma en temps "pararéel"", Comptes Rendus de l'Académie des Sciences - Series I - Mathematics (2001)

Solve 
$$\frac{du}{dt}(t) = F(u(t)), \quad u(0) = u_0$$

Parareal iteration:

 $N_{\Delta T}$ 

- Sequential
- Parallel fine corrections
- $G_{\Delta t}$  and  $\mathcal{F}_{\delta t}$  user-defined schemes





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#### $\square$ $N_{\Delta T}$ time slices

- Sequential coarse prediction
- □ Parallel fine corrections
- $\square \ \mathcal{G}_{\Delta t}$  and  $\mathcal{F}_{\delta t}$ : user-defined schemes







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$$t_0 = 0 \qquad t_1 \qquad t_2 \qquad t_{N_{\Delta T}} = T$$





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 $t_1$ 

S. Friedhoff et al., "A Multigrid-in-Time Algorithm for Solving Evolution Equations in Parallel", Presented at: Sixteenth Copper Mountain Conference on Multigrid Methods (2013)

#### Multilevel PInT approach inspired on spatial multigrid (MGR)

- User-defined time stepping schemes
- Solution is iteratively improved using the Full Approximation Scheme (FAS):





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#### Several parameters to be set:

- Number of levels
- <sup> $\Box$ </sup> Relaxation strategy: F, FCF, FCFCF, ..., F(CF)<sup> $N_{relax}$ </sup>
- Cycling strategy: V-, W-, F-cycles
- □ .





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Trade-off: convergence rate vs computational cost

Parareal  $\equiv$  MGRIT with specific parameters





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- Successful application to parabolic, diffusive problems;
- Hyperbolic problems: instabilities and slow convergence;
- Causes:
  - Mismatch of coarse and fine discrete phase speeds;
  - □ Mainly on high wavenumbers of the solution





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A. Schmitt et al., "A numerical study of a semi-Lagrangian Parareal method applied to the viscous Burgers equation", *Computing and Visualization in Science* (2018)

Semi-Lagrangian treatment of advection: follow characteristics and interpolate solution from Eulerian grid



Improved stability  $\implies$  large time steps

 Viscous 1D Burgers: improved stability and convergence of Parareal with SL as coarse scheme [Schmitt et al. (2018)]

 Linear advection: "coarse-grid operators should take into account the behavior of the hyperbolic problem by tracking the characteristic curves" [De Sterck et al. (2021)]





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  J. G. Caldas Steinstraesser PInT for fluyd dynamics

Feng Chen, Jan S. Hesthaven, and Xueyu Zhu, "On the Use of Reduced Basis Methods to Accelerate and Stabilize the Parareal Method", *Reduced Order Methods for Modeling and Computational Reduction* (2014)

#### Replace coarse timestepping scheme by a reduced-order model (ROM):

- Low-dimensional approximation for the fine model
- $^{\square}\,$  Solved with the same small time step  $\delta t$  of  $\mathcal{F}_{\delta t}$
- $\square$  Constructed from snapshots of the fine solution





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$$u_{n+1}^{k+1} = \mathcal{G}_{\Delta t}(u_n^{k+1}) + \mathcal{F}_{\delta t}(u_n^k) - \mathcal{G}_{\Delta t}(u_n^k) \implies u_{n+1}^{k+1} = \mathcal{R}_{\delta t}^k(u_n^{k+1}) + \mathcal{F}_{\delta t}(u_n^k) - \mathcal{R}_{\delta t}^k(u_n^k)$$

$$\begin{array}{c} \frac{dy_1}{dt} = Ay_1 + F(y_1) \\ \frac{dy_2}{dt} = Ay_2 + F(y_2) \\ \vdots \\ \vdots \\ \frac{dy_M}{dt} = Ay_M + F(y_M) \end{array} \implies \begin{array}{c} \overbrace{\begin{array}{c} \mathbf{Snapshots} \\ \mathbf{y}(t_1), \mathbf{y}(t_2), \dots, \mathbf{y}(t_N) \\ \mathbf{y}(t_1) = \widetilde{A}\widetilde{y}_1 + \widetilde{F}(\widetilde{y}_1) \\ \vdots \\ \frac{d\widetilde{y}_m}{dt} = \widetilde{A}\widetilde{y}_m + \widetilde{F}(\widetilde{y}_m) \\ m \ll M \end{array}}$$





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- Improvement of stability and convergence if the ROM successfully captures the fine dynamics
- Drawback: model reduction may be expensive





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- Shallow water equations on the plane
- Explicit-in-time finite volume scheme
- Challenges: large spatial and temporal domains, discontinuous solutions
- PInT with Parareal and ROM-based Parareal

$$\begin{split} \frac{\partial}{\partial t} \left( \boldsymbol{U}(t) \right) &+ \frac{\partial}{\partial x} \left( \boldsymbol{F}(\boldsymbol{U}(t)) \right) + \frac{\partial}{\partial y} \left( \boldsymbol{G}(\boldsymbol{U}(t)) \right) = \boldsymbol{S}(\boldsymbol{U}(t)) \\ \boldsymbol{U} &= \begin{pmatrix} h \\ h u_x \\ h u_y \end{pmatrix}, \quad \boldsymbol{F}(\boldsymbol{U}) = \begin{pmatrix} h u_x \\ h u_x^2 + g h^2 / 2 \\ h u_x u_y \end{pmatrix}, \\ \boldsymbol{G}(\boldsymbol{U}) &= \begin{pmatrix} h u_y \\ h u_x^2 + g h^2 / 2 \\ h u_y^2 + g h^2 / 2 \end{pmatrix}, \quad \boldsymbol{S}(\boldsymbol{U}) = \begin{pmatrix} 0 \\ S_{0,x} + S_{f,x} \\ S_{0,y} + S_{f,y} \end{pmatrix} \end{split}$$



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### **Application: urban floods**

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Ongoing work with Pedro Peixoto and Martin Schreiber

#### Climate modelling and numerical weather prediction

- Shallow water equations on the rotating sphere
- Spatial discretization using spherical harmonics
- Challenges: large domains, development of small-scale spatial features





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$$\begin{split} \frac{\partial}{\partial t} U &= L_G U + L_C U + N_A (U) + N_R (U) \\ &= L U + N (U) \end{split}$$

$$\begin{split} \boldsymbol{U} &= \begin{pmatrix} \Phi \\ \xi \\ \delta \end{pmatrix}, \qquad \boldsymbol{L}_{\boldsymbol{G}}(\boldsymbol{U}) = \begin{pmatrix} \overline{\Phi}\delta \\ 0 \\ -\nabla^{2}\Phi \end{pmatrix}, \qquad \boldsymbol{L}_{\boldsymbol{C}}(\boldsymbol{U}) = \begin{pmatrix} 0 \\ -\nabla \cdot (f\boldsymbol{V}) \\ -\boldsymbol{k} \cdot \nabla \times (f\boldsymbol{V}) \end{pmatrix} \\ \boldsymbol{N}_{\boldsymbol{A}}(\boldsymbol{U}) &= \begin{pmatrix} -\boldsymbol{V} \cdot \nabla \Phi \\ -\nabla \cdot (\xi\boldsymbol{V}) \\ \nabla^{2} \left(\frac{\boldsymbol{V} \cdot \boldsymbol{V}}{2}\right) + \boldsymbol{k} \cdot \nabla \times (\xi\boldsymbol{V}) \end{pmatrix}, \qquad \boldsymbol{N}_{\boldsymbol{R}}(\boldsymbol{U}) = \begin{pmatrix} -\Phi'\delta \\ 0 \\ 0 \end{pmatrix} \end{split}$$





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$$\begin{split} &\frac{\partial}{\partial t} \boldsymbol{U} = \boldsymbol{L}_{\boldsymbol{G}} \boldsymbol{U} + \boldsymbol{L}_{\boldsymbol{C}} \boldsymbol{U} + \boldsymbol{N}_{\boldsymbol{A}}(\boldsymbol{U}) + \boldsymbol{N}_{\boldsymbol{R}}(\boldsymbol{U}) \\ &= \boldsymbol{L} \boldsymbol{U} + \boldsymbol{N}(\boldsymbol{U}) \end{split}$$

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Two- and multilevel PinT (Parareal and MGRIT)

$$\frac{\partial \boldsymbol{U}}{\partial t} = \boldsymbol{L}\boldsymbol{U} + \boldsymbol{N}(\boldsymbol{U})$$

Which coarse time integration method?





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Implicit-Explicit (IMEX)

$$\boldsymbol{U}^{n+1} = \boldsymbol{F}_{E}^{\Delta t/2} \left( \boldsymbol{F}_{I}^{\Delta t} \left( \boldsymbol{F}_{E}^{\Delta t/2} \left( \boldsymbol{U}^{n} \right) \right) \right)$$

Linear term: implicit

Nonlinear term: explicit





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Implicit-Explicit (IMEX)

SL-SI-SETTLS [Hortal (2002)]  $\frac{U^{n+1} - U_*^n}{\Delta t} = \frac{1}{2} \left( LU^{n+1} + LU_*^n \right) + N^{n+1/2}$ ■ Semi-Lagrangian + semi-implicit

Operational use in IFS-ECMWF





Ongoing work with Pedro Peixoto and Martin Schreiber

Two- and multilevel PinT (Parareal and MGRIT)

$$\frac{\partial \boldsymbol{U}}{\partial t} = \boldsymbol{L}\boldsymbol{U} + \boldsymbol{N}(\boldsymbol{U})$$

- Which coarse time integration method?
  - Implicit-Explicit (IMEX)
  - SL-SI-SETTLS [Hortal (2002)]
  - Exponential integration: ETDRK [Cox and Matthews (2002)]

$$\boldsymbol{U}^{n+1} = e^{\Delta t \boldsymbol{L}} \boldsymbol{U}^n + e^{\Delta t \boldsymbol{L}} \int_{t_n}^{t_{n+1}} e^{-(s-t_n)\boldsymbol{L}} \boldsymbol{N}(\boldsymbol{U}(s)) ds \implies$$

$$\begin{cases} \boldsymbol{U}_{\text{ETDIRK}}^{n+1} = \varphi_0(\Delta t \boldsymbol{L}) \boldsymbol{U}^n + \Delta t \varphi_1(\Delta t \boldsymbol{L}) \boldsymbol{N}(\boldsymbol{U}^n) \\ \boldsymbol{U}_{\text{EDT2RK}}^{n+1} = \boldsymbol{U}_{\text{ETDIRK}}^{n+1} + \Delta t \varphi_2(\Delta t \boldsymbol{L}) \left[ \boldsymbol{N}(\boldsymbol{U}_{\text{ETDIRK}}^{n+1}) - \boldsymbol{N}(\boldsymbol{U}^n) \right] \end{cases}$$

- Linear term solved exactly
- Approximation for the nonlinear term
- $\varphi_k$ : matrix exponential functions





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Two- and multilevel PinT (Parareal and MGRIT)

$$\frac{\partial \boldsymbol{U}}{\partial t} = \boldsymbol{L}\boldsymbol{U} + \boldsymbol{N}(\boldsymbol{U})$$

- Which coarse time integration method?
  - Implicit-Explicit (IMEX)
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  - Exponential integration: ETDRK [Cox and Matthews (2002)]

 $\begin{bmatrix} \mathbf{SL} & - \mathbf{Exponential integration: SL-ETDRK [Peixoto and Schreiber (2019)]} \\ U_{\mathsf{SL}-\mathsf{ETDIRK}}^{n+1} &= \varphi_0(\Delta tL) \left[ U^n + \Delta t \psi_1(\Delta tL) \tilde{N}(U^n) \right]_*^n \\ U_{\mathsf{SL}-\mathsf{ETDIRK}}^{n+1} &= U_{\mathsf{SL}-\mathsf{ETDIRK}}^{n+1} + \Delta t \varphi_0(\Delta tL) \left[ \psi_2(\Delta tL) \tilde{N}(U_{\mathsf{SL}-\mathsf{ETDIRK}}^{n+1}) - \left( \psi_2(\Delta tL) \tilde{N}(U^n) \right)_*^n \right] \\ \end{bmatrix}$ 

- SL-version of ETDRK
- Improved stability



Ongoing work with Pedro Peixoto and Martin Schreiber

Stability analysis:

 $\Box$  Consider the ODE (e.g. spectral discretization) and its linearization:

$$\frac{\partial u}{\partial t} = \lambda_L u + N(u), \qquad \frac{\partial u}{\partial t} = \lambda_L u + \lambda_N u$$

<sup>¬</sup> Stability in function of  $\xi_L := \lambda_L \Delta t \in \mathbb{C}$  and  $\xi_N := \lambda_N \Delta t \in \mathbb{C}$ :

 $|A_{\mathsf{scheme}}(\xi_L, \xi_N)| \le 1$ 

where

$$u^{n+1} = A_{\text{scheme}} u^n$$

Plot stability regions in function of  $Re(\xi_N)$  and  $Im(\xi_N)$  for fixed  $\xi_L = 0$ (geostrophic mode) and  $\xi_L \in i\mathbb{R}^*$  (inertia-gravity modes)



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Ongoing work with Pedro Peixoto and Martin Schreiber

- Stability of Parareal [Staff and Rønquist (2005)]
  - Fine scheme: timestep  $\delta t$  and stability function  $A_f$
  - $^{\Box}$  Coarse scheme: timestep  $\Delta t = m \delta t$  and stability function  $A_c$

$$u_{n}^{k} = \mathcal{G}_{\Delta t}(u_{n-1}^{k}) + \mathcal{F}_{\delta t}(u_{n-1}^{k-1}) - \mathcal{G}_{\Delta t}(u_{n-1}^{k-1})$$
$$\Rightarrow u_{n}^{k} = A_{c}u_{n-1}^{k} + (A_{f}^{m} - A_{c})u_{n+1}^{k-1}$$

$$u_n^k = \underbrace{\left(\sum_{i=0}^k \binom{n}{i} \left(A_f^m - A_c\right)^i (A_c)^{n-i}\right)}_{A_{\text{accurated}}} u_0$$





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=  $u_n^k = \mathcal{A}_{\delta u_n^k} + (\mathcal{A}_n^k - \mathcal{A}_{\delta u_n^k})$ 

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$$u_n^k = \underbrace{\left(\sum_{i=0}^k \binom{n}{i} \left(A_f^m - A_c\right)^i (A_c)^{n-i}\right)}_{A_{\text{normal}}} u_0$$





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$$u_n^k = \underbrace{\left(\sum_{i=0}^k \binom{n}{i} \left(A_f^m - A_c\right)^i (A_c)^{n-i}\right)}_{A_{\text{parareal}}} u_0$$





Ongoing work with Pedro Peixoto and Martin Schreiber

- Stability of Parareal along iterations
  - □ Fine scheme: IMEX
  - □ Coarse scheme: IMEX, SL-SI-SETTLS, ETD2RK, SL-ETD2RK

n = 2, m = 100





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#### Loss of stability with SL-SI-SETTLS





Ongoing work with Pedro Peixoto and Martin Schreiber

Stability of MGRIT (two levels with F(CF)<sup>N<sub>relax</sub></sup>)



Recurrence relation:

$$\boldsymbol{u}_{n}^{k} = \underbrace{\left( \sum_{i=0}^{\lfloor k/(N_{\text{relax}}+1) \rfloor} \left( \begin{array}{c} n-iN_{\text{relax}} \\ i \end{array} \right) \boldsymbol{A}_{f}^{mN_{\text{relax}}} \left( \boldsymbol{A}_{f}^{m} - \boldsymbol{A}_{c} \right)^{i} \boldsymbol{A}_{c}^{n-i(N_{\text{relax}}+1)} \right)}_{\boldsymbol{u}_{0}} \boldsymbol{u}_{0}$$

AMGRIT





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Stability of MGRIT (two levels with F(CF)<sup>N<sub>relax</sub></sup>)



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 $\Box$  n = 2, m = 100, k = 5





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Fine scheme: IMEX

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Ongoing work with Pedro Peixoto and Martin Schreiber

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Fine scheme: IMEX

Coarse scheme: IMEX, SL-SI-SETTLS, ETD2RK, SL-ETD2RK

$$n = 2, m = 100, k = 5$$

#### Increasing stability with more expensive relaxation



Ongoing work with Pedro Peixoto and Martin Schreiber

#### Test case: Gaussian bump

- □ T = 102400
- $\square$  Reference solution:  $\delta t = 60$ , spectral resolution M = 256
- □ Coarse levels: coarsening factor m, spectral resolution  $M_{\text{coarse}} = 128$
- Artificial diffusion
- $^{\Box}$  Reference solution (geopotential field  $\Phi$ ):





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#### Test case: Gaussian bump

Errors in function of the coarse time stepping method

 $N_{\text{levels}} = 2$ , m = 2,  $N_{\text{relax}} = 4$ 







Ongoing work with Pedro Peixoto and Martin Schreiber

#### Test case: Gaussian bump

 $N_{\text{levels}} = 2, m = 2, N_{\text{relax}} = 4$ 

IME

Errors in function of the coarse time stepping method



More levels ⇒ larger timestep in coarsest level ⇒ stability issues
 More convergence and stability with exponential methods, mainly SL





 $N_{\text{levels}} = 3, m = 4, N_{\text{relay}} = 1$ 

Ongoing work with Pedro Peixoto and Martin Schreiber

#### Test case: Gaussian bump

 $N_{\text{levels}} = 2, m = 2, N_{\text{relax}} = 4$ 

IME

Errors in function of the coarse time stepping method



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 More convergence and stability with exponential methods, mainly SL





 $N_{\text{levels}} = 3, m = 4, N_{\text{relay}} = 1$ 

Ongoing work with Pedro Peixoto and Martin Schreiber

#### Test case: Gaussian bump

Errors in function of  $N_{\rm relax}$ 

 $N_{\text{levels}} = 2$ , m = 2, coarse time stepping method: SL-ETD2RK






Ongoing work with Pedro Peixoto and Martin Schreiber

#### Test case: Gaussian bump

Errors in function of  $N_{\rm relax}$ 

 $N_{\text{levels}} = 2$ , m = 2, coarse time stepping method: SL-ETD2RK



- Better convergence with more expensive relaxation;
- Convergence vs computational cost?



Ongoing work with Pedro Peixoto and Martin Schreiber

#### Test case: Gaussian bump

Relative error of geopotential  $\Phi$  at t = T:







Ongoing work with Pedro Peixoto and Martin Schreiber

#### Test case: Gaussian bump

Relative error of geopotential  $\Phi$  at t = T:







Ongoing work with Pedro Peixoto and Martin Schreiber

#### Test case: Gaussian bump

Relative error of geopotential  $\Phi$  at t = T:



🚯 IME



- Demands from operational applications
- Challenges due to hyperbolic nature
- Configurations for improving convergence and stability
  - Choice of coarse time stepping method
  - Multilevel and relaxation strategies
- Trade-off with computational cost
- Application to atmospheric circulation models
  - Promising results using SL-EXP methods
  - More complex problems?
  - Convergence and stability of small-scale spatial features are still a bottleneds
  - Parallel implementation and evaluation of feasibility in practices
  - Evaluation of influence of artificial diffusion





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Parallel-in-time for fluid dynamics

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J. G. Caldas Steinstraesser - PInT for fluyd dynamics



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J. G. Caldas Steinstraesser - PInT for fluyd dynamics



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  - □ Promising results using SL-EXP methods
  - □ More complex problems?
  - □ Convergence and stability of small-scale spatial features are still a bottleneck
  - Parallel implementation and evaluation of feasibility in practice
  - Evaluation of influence of artificial diffusion





# Thank you!

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### Outline

Introduction

#### • Parallel-in-time methods

- Parareal
- MGRIT
- Some ideas for improving PinT
- Applications
  - Urban floods
  - Atmospheric circulation models





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