

SUPERFÍCIES EM $\mathbb{R}^3$

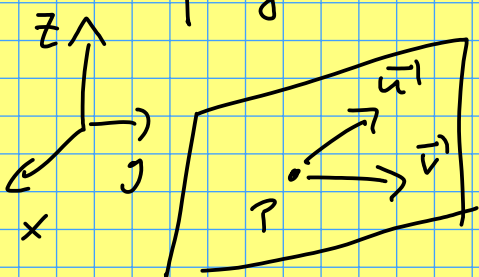
08/11/21

(& SUAS PARAMETRIZAÇÕES)

Exemplos

1. Plano em $\mathbb{R}^3$

Eq. geral $ax + by + cz = d$



Eqs. paramétricas

$$\sigma : \begin{cases} x = x_0 + \lambda a_1 + \mu a_2 \\ y = y_0 + \lambda b_1 + \mu b_2 \\ z = z_0 + \lambda c_1 + \mu c_2 \end{cases} \quad \begin{matrix} \lambda, \mu \in \mathbb{R} \\ \text{parâmetros} \end{matrix}$$

$P = (x_0, y_0, z_0) \leftarrow$ um ponto do plano

$$\vec{u} = (a_1, b_1, c_1)$$

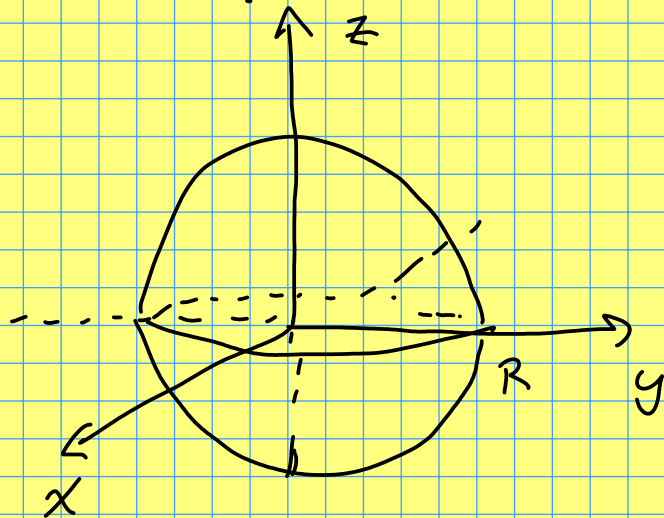
$$\vec{v} = (a_2, b_2, c_2)$$

} vetores diretores do plano

$$\sigma \left(\begin{matrix} \lambda \\ \mu \end{matrix} \right) = (x_0 + \lambda a_1 + \mu a_2, y_0 + \lambda b_1 + \mu b_2, z_0 + \lambda c_1 + \mu c_2)$$

$\sigma : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ parametrização do plano

2. Esfera em $\mathbb{R}^3$



$$\sigma: \begin{cases} x = R \cos \theta \sin \varphi \\ y = R \sin \theta \sin \varphi \\ z = R \cos \varphi \end{cases}$$

(coords esféricas)

θ, φ : parâmetros

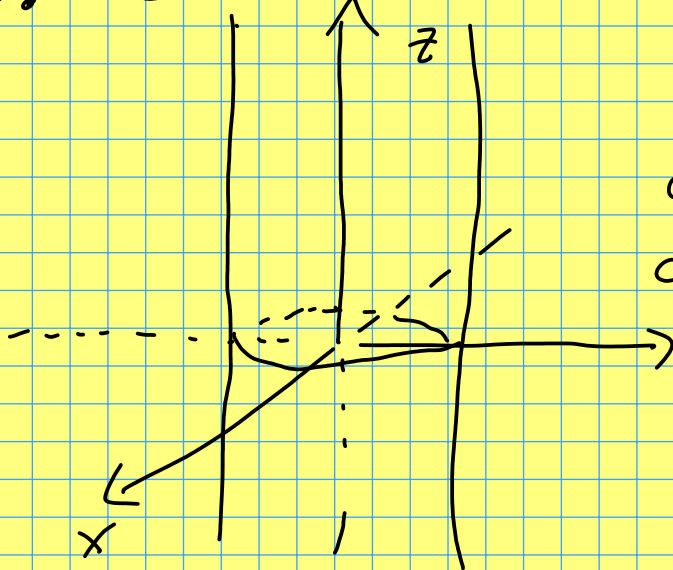
θ : longitude $\theta \in [0, 2\pi]$

φ : co-latitude $\varphi \in [0, \pi]$

$$\sigma : \underbrace{[0, 2\pi] \times [0, \pi]}_{\text{retângulo em } \mathbb{R}^2} \rightarrow \mathbb{R}^3$$

3. Cilindro

$$x^2 + y^2 = R^2$$

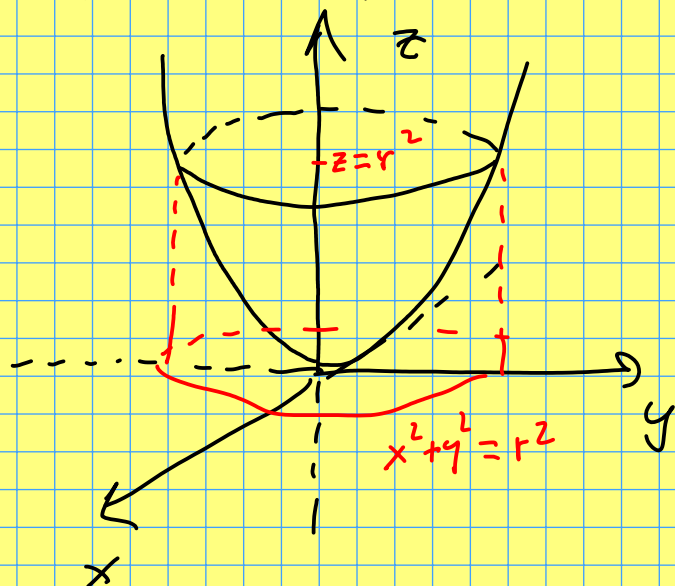


cilindro vertical
circular reto

$$\sigma: \begin{cases} x = R \cos \theta \\ y = R \sin \theta \\ z = h \end{cases} \quad \begin{matrix} h \in \mathbb{R} \\ 0 \leq \theta \leq 2\pi \end{matrix}$$

(coords. cilíndricas)

4. Parabolóide de revolução $z = \underbrace{x^2 + y^2}_{(\text{dist ao eixo } z)^2}$

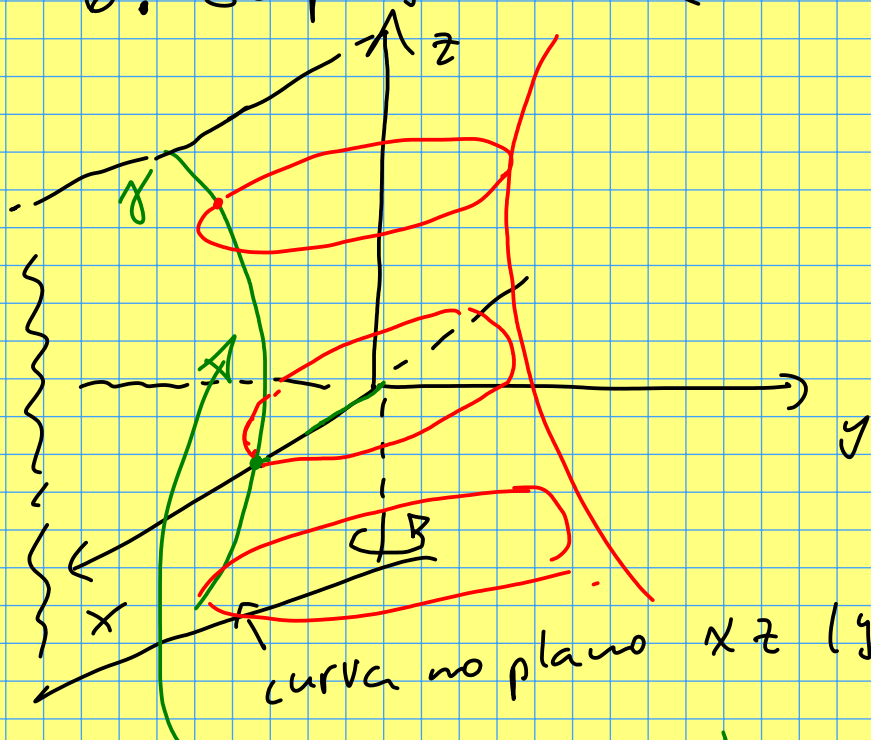


$$\sigma : \begin{cases} x = u \\ y = v \\ z = u^2 + v^2 \end{cases}$$

5. Graficos $z = f(x, y)$ $u, v \in \mathbb{R}$
 $f: \Omega \subset \mathbb{R}^2 \rightarrow \mathbb{R}$

$$\sigma : \begin{cases} x = u \\ y = v \\ z = f(u, v) \end{cases} \quad (u, v) \in \Omega$$

6. Superfícies de revolução



curva no plano xz ($y=0$)

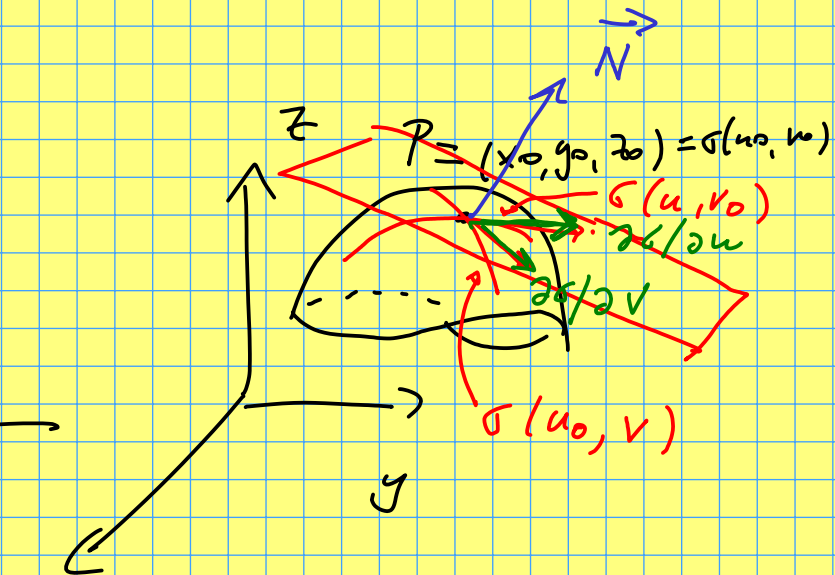
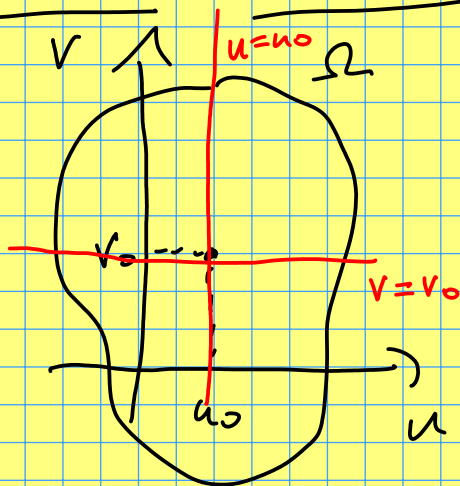
$$\gamma(u) = (f(u), 0, g(u)) \quad u \in I$$

$$\begin{pmatrix} \cos v & -\sin v & 0 \\ \sin v & \cos v & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} f(u) \\ 0 \\ g(u) \end{pmatrix} = \begin{pmatrix} f(u) \cos v \\ f(u) \sin v \\ g(u) \end{pmatrix}$$

$$\sigma: \begin{cases} x = f(u) \cos v \\ y = f(u) \sin v \\ z = g(u) \end{cases} \quad \begin{matrix} u \in I \\ v \in [0, 2\pi] \end{matrix}$$

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PLANO TANGENTE



$$\sigma: \begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases} \quad (u, v) \in \Omega$$

Eq. vetorial do plano
tangente à superfície no ponto P:

$$(x, y, z) = (x_0, y_0, z_0) + \lambda \frac{\partial \sigma}{\partial u}(u_0, v_0) + \mu \frac{\partial \sigma}{\partial v}(u_0, v_0)$$

$$\lambda, \mu \in \mathbb{R}$$

$\frac{\partial \sigma}{\partial u}(u_0, v_0), \frac{\partial \sigma}{\partial v}(u_0, v_0)$: vetores diretores do plano tangente

$$\vec{N} = \frac{\partial \sigma}{\partial u} \times \frac{\partial \sigma}{\partial v} \quad (\text{produto vetorial})$$

é um vetor normal à superfície

$$\left[\begin{array}{l} \text{Obs } \vec{N} \neq \vec{0} \Leftrightarrow \frac{\partial \sigma}{\partial u}, \frac{\partial \sigma}{\partial v} \text{ s\~ao L.I.} \\ \text{Neste caso, } \vec{n} = \frac{\vec{N}}{\|\vec{N}\|} \text{ é um vetor normal unit\~ario.} \end{array} \right]$$

$$\text{Se } \sigma: \begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases} \quad (u, v) \in \Omega$$

$$\text{ent\~ao } \frac{\partial \sigma}{\partial u} = \left(\frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \right) \text{ e}$$

$$\frac{\partial \sigma}{\partial v} = \left(\frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v} \right).$$

$$\vec{N} = \frac{\partial \sigma}{\partial u} \times \frac{\partial \sigma}{\partial v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & \frac{\partial z}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & \frac{\partial z}{\partial v} \end{vmatrix}$$

$$= \left(\frac{\partial y}{\partial u} \frac{\partial z}{\partial v} - \frac{\partial y}{\partial v} \frac{\partial z}{\partial u}, \frac{\partial z}{\partial u} \frac{\partial x}{\partial v} - \frac{\partial z}{\partial v} \frac{\partial x}{\partial u}, \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u} \right)$$

$$= \left(\begin{vmatrix} \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} \end{vmatrix}, \begin{vmatrix} \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} \\ \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \end{vmatrix}, \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \right)$$

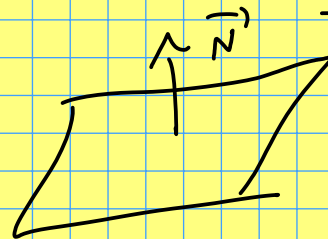
$$= \left(\frac{\partial(y, z)}{\partial(u, v)}, \frac{\partial(z, x)}{\partial(u, v)}, \frac{\partial(x, y)}{\partial(u, v)} \right)$$

Cálculo de $\vec{N}$ nos exemplos:

1. $\frac{\partial \sigma}{\partial \lambda} = (a_1, b_1, c_1) = \vec{u}$

$\frac{\partial \sigma}{\partial \mu} = (a_2, b_2, c_2) = \vec{v}$

$\vec{N} = \vec{u} \times \vec{v}$ constante



2.

$$r: \begin{cases} x = R \cos \theta \sin \varphi \\ y = R \sin \theta \sin \varphi \\ z = R \cos \varphi \end{cases}$$

$$\vec{N} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial x}{\partial \theta} & \frac{\partial y}{\partial \theta} & \frac{\partial z}{\partial \theta} \\ \frac{\partial x}{\partial \varphi} & \frac{\partial y}{\partial \varphi} & \frac{\partial z}{\partial \varphi} \end{vmatrix} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -R \sin \theta \sin \varphi & R \cos \theta \sin \varphi & 0 \\ R \cos \theta \cos \varphi & R \sin \theta \cos \varphi & -R \sin \varphi \end{vmatrix}$$

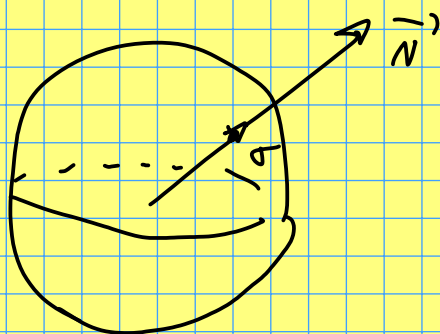
$$= R^2 \sin \varphi \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -\sin \theta & \cos \theta & 0 \\ \cos \theta \cos \varphi & \sin \theta \cos \varphi & -\sin \varphi \end{vmatrix}$$

$$= R^2 \sin \varphi (-\cos \theta \sin \varphi, -\sin \theta \sin \varphi, -\cos \varphi)$$

$$= -R \sin \varphi \underbrace{(R \cos \theta \sin \varphi, R \sin \theta \sin \varphi, R \cos \varphi)}_{\sigma(\theta, \varphi)}$$

$$\rightarrow N(\theta, \varphi) = -R \sin \varphi \cdot \sigma(\theta, \varphi)$$

"A normal é um múltiplo do vetor posição"



$$\|\vec{N}\| = |R \sin \varphi| \|\sigma\| = R \sin \varphi \cdot R = R^2 \sin \varphi$$

$$0 \leq \varphi \leq \pi$$

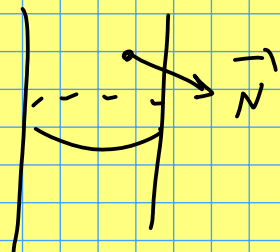
3.

$$\sigma: \begin{cases} x = R \cos \theta \\ y = R \sin \theta \\ z = h \end{cases}$$

$$\vec{N} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -\partial x / \partial \theta & - & - \\ -\partial g / \partial h & - & - \end{vmatrix} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -R \sin \theta & R \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

$$= (R \cos \theta, R \sin \theta, 0)$$

$\vec{N}$ é um vetor horizontal



5. Gráfico $z = f(x, y)$ $(x, y) \in \Omega$

$$\sigma: \begin{cases} x = u \\ y = v \\ z = f(u, v) \end{cases} \quad (u, v) \in \Omega$$

$$\vec{N} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & \partial f / \partial u \\ 0 & 1 & \partial f / \partial v \end{vmatrix} = \left(-\frac{\partial f}{\partial u}, -\frac{\partial f}{\partial v}, 1 \right)$$

$$\|\vec{N}\| = \sqrt{1 + \left(\frac{\partial f}{\partial u} \right)^2 + \left(\frac{\partial f}{\partial v} \right)^2}$$

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LISTA 7

§ 21.2

$$11. \int_{(-2, -1)}^{(1, 5)} 2y dx + 2x dy$$

Resolução: Cálculo de função potencial

$$\begin{cases} \frac{\partial \varphi}{\partial x} = 2y \Rightarrow \int \frac{\partial \varphi}{\partial x} dx = \int 2y dx \end{cases}$$

$$\varphi(x, y) = 2xy + h(y)$$

$$\begin{cases} \frac{\partial \varphi}{\partial y} = 2x \end{cases}$$

$$2x = \frac{\partial \varphi}{\partial y} = 2x + h'(y)$$

$$0 = h'(y) \Rightarrow h(y) = C$$

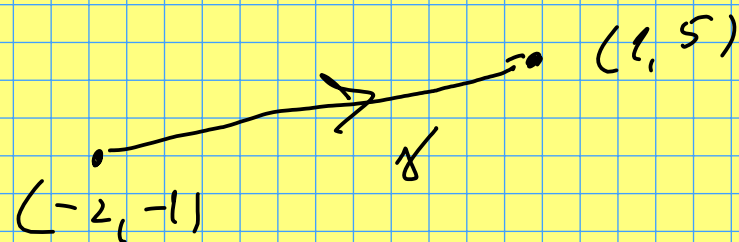
$$\therefore \varphi(x, y) = 2xy + C$$

é uma função potencial para $\vec{F} = 2y\vec{i} + 2x\vec{j}$.

$$\text{De fato: } \nabla \varphi = \left(\frac{\partial \varphi}{\partial x}, \frac{\partial \varphi}{\partial y} \right) = (2y, 2x) = \vec{F}(x, y)$$

$\vec{F}$ é um campo gradiente. $\vec{F}$ é conservativo

$$\therefore \int_{(-2, -1)}^{(1, 5)} \vec{F} d\vec{r} \text{ independente do caminho.}$$



$$\gamma(t) = (-2, -1) + t((1, 5) - (-2, -1))$$

$$= (-2, -1) + t(3, 6)$$

$$\gamma: \begin{cases} x = -2 + 3t \\ y = -1 + 6t \end{cases} \quad 0 \leq t \leq 1$$

$$\int_{(-2, -1)}^{(1, 5)} 2y dx + 2x dy = \int_{\gamma} 2y dx + 2x dy$$

$$= \int_0^1 2(-1+6t)3 + 2(-2+3t)6 dt$$

$$= \int_0^1 -6 + 36t - 24 + 36t dt$$

$$= \int_0^1 -30 + 72t dt = 6 \int_0^1 -5 + 12t dt$$

$$= 6 \left. -5t + 6t^2 \right|_0^1 = 6$$

Alternativamente:

$$\int_{(-2, -1)}^{(1, 5)} 2y dx + 2x dy = \varphi(1, 5) - \varphi(-2, -1)$$

$$= 2 \cdot 1.5 - 2(-2)(-1)$$

$$\varphi(x, y) = 2xy$$

$$= 10 - 4$$

$$= 6 //$$