# G-STRUCTURE PRESERVING AFFINE AND ISOMETRIC IMMERSIONS

#### Joint work with Daniel V. Tausk, USP

Paolo Piccione

Departamento de Matemática Instituto de Matemática e Estatística Universidade de São Paulo

#### Workshop on Differential Geometry and PDEs

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Paolo Piccione (IME–USP)

G-structures and affine immersions

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Given a *G*-structure *P* on *X* and a *G*-structure *Q* on *Y*, a map  $f: X \rightarrow Y$  is *G*-structure preserving if  $f \circ p \in Q$  for all  $p \in P$ .

Example (1)

V n-dimensional vector space

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A frame is an iso  $p : \mathbb{R}^n \to V$ ,  $FR(V) \subset Bij(\mathbb{R}^n, V)$ 

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Given a *G*-structure  $P \subset \text{Bij}(X_0, X)$  and a subgroup  $H \subset G$ , there are [G : H] strengthening *H*-structures of *P*.

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- $\operatorname{FR}_{V_0}(V)$  is a principal space with structural group  $\operatorname{GL}(V_0)$ .

# Outline

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- 3 Principal fiber bundles
- 4 Connections
- Inner torsion of a G-structure
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There exists a unique differentiable structure on P that makes the action of G on P smooth,  $\Pi$  a smooth submersion,  $P_x$  a smooth submanifold, every admissible local section  $s : U \subset M \to P$  smooth,.

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 $\operatorname{Ver}_{\rho} = \operatorname{Ker}(d\Pi_{\rho}) \subset T_{\rho}P$  vertical space;

canonical isomorphism  $d\beta_p(1) : \mathfrak{g} \xrightarrow{\cong} \operatorname{Ver}_p P$ .

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• *pull-backs*:  $\Pi : P \to M$  principal fiber bundle,  $f : M' \to M$  smooth map,  $f^*P = \bigcup_{y \in M'} (\{y\} \times P_{f(y)})$ .

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**Def.:** A G-structure on E is a G-principal subbundle of FR(E).

# Outline

## G-structures

- 2 Principal spaces
- 3 Principal fiber bundles
- 4 Connections
- 5 Inner torsion of a *G*-structure
- 6 Infinitesimally homogeneous affine manifolds with *G*-structure
- 7 Immersion theorems

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#### **Properties of principal connections**

- can be pushed forward
- induce connections on all associated bundles.

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   Principal connections on FR(E)
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### Curvature and torsion

*Curvature tensor* of  $\nabla$ :  $R : \Gamma(TM) \times \Gamma(TM) \times \Gamma(E) \longrightarrow \Gamma(E)$ 

$$R(X,Y)\epsilon = \nabla_X \nabla_Y \epsilon - \nabla_Y \nabla_X \epsilon - \nabla_{[X,Y]} \epsilon$$

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When E = TM, torsion:  $T(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y]$ .

 $\nabla$  is *symmetric* if T = 0

Gauss, Codazzi and Ricci equations  $\pi_1 : E^1 \to M$  and  $\pi_2 : E^2 \to M$  vector bundle. *Whitney sum*:  $\pi : E = E_1 \oplus E_2 \to M$ ,  $pr_i : E \to E^i$  projection.

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 $\mathrm{pr}_{1}(R(X,Y)\epsilon_{1}) = R_{1}(X,Y)\epsilon_{1} + \alpha^{1}(X,\alpha^{2}(Y,\epsilon_{1})) - \alpha^{1}(Y,\alpha^{2}(X,\epsilon_{1}))$ 

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 $pr_1(R(X, Y)\epsilon_1) = R_1(X, Y)\epsilon_1 + \alpha^1(X, \alpha^2(Y, \epsilon_1)) - \alpha^1(Y, \alpha^2(X, \epsilon_1))$ Codazzi equations

 $\begin{aligned} & \operatorname{pr}_2\big(R(X,Y)\epsilon_1\big) = \nabla\alpha^2(X,Y,\epsilon_1) - \nabla\alpha^2(Y,X,\epsilon_1) + \alpha^2\big(T(X,Y),\epsilon_1\big) \\ & \operatorname{pr}_1\big(R(X,Y)\epsilon_2\big) = \nabla\alpha^1(X,Y,\epsilon_2) - \nabla\alpha^1(Y,X,\epsilon_2) + \alpha^1\big(T(X,Y),\epsilon_2\big) \end{aligned}$ 

Gauss, Codazzi and Ricci equations  $\pi_1 : E^1 \to M$  and  $\pi_2 : E^2 \to M$  vector bundle. *Whitney sum*:  $\pi : E = E_1 \oplus E_2 \to M$ ,  $\operatorname{pr}_i : E \to E^i$  projection.  $\nabla$  connection on E. Given sections  $\epsilon^i \in \Gamma(E^i)$ : •  $\nabla^1_X \epsilon_1 = \operatorname{pr}_1(\nabla_X \epsilon_1)$  connection in  $E^1$ •  $\nabla^2_X \epsilon_1 = \operatorname{pr}_2(\nabla_X \epsilon_2)$  connection in  $E^2$ •  $\alpha^1(X, \epsilon_2) = \operatorname{pr}_1(\nabla_X \epsilon_2)$ , tensor  $\alpha^1_x : T_x M \times E^2_x \to E^1_x$ •  $\alpha^2(X, \epsilon_1) = \operatorname{pr}_2(\nabla_X \epsilon_1)$ , tensor  $\alpha^2_x : T_x M \times E^1_x \to E^2_x$ Gauss equation:

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Codazzi equations

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#### **Ricci equation**

$$\mathrm{pr}_{2}(R(X,Y)\epsilon_{2}) = R_{2}(X,Y)\epsilon_{2} + \alpha^{2}(X,\alpha^{1}(Y,\epsilon_{2})) - \alpha^{2}(Y,\alpha^{1}(X,\epsilon_{2}))$$

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## Outline

### G-structures

- 2 Principal spaces
- 3 Principal fiber bundles
- 4 Connections
- 5 Inner torsion of a *G*-structure
- 6 Infinitesimally homogeneous affine manifolds with *G*-structure

#### 7 Immersion theorems

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Paolo Piccione (IME-USP)

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- $G_x = \{T \in \operatorname{GL}(E_x) : T \circ \rho \in P_x, \forall \rho \in P_x\}, \mathfrak{g}_x = \operatorname{Lie}(G_x).$

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The inner torsion  $\mathfrak{I}_{X}^{P}: T_{X}M \to \mathfrak{gl}(E_{X})/\mathfrak{g}_{X}$  is:

$$T_{X}M \xrightarrow{\mathcal{I}_{X}^{P}} \mathfrak{gl}(E_{X}) \xrightarrow{\mathfrak{gl}(E_{X})/\mathfrak{g}_{X}} \mathfrak{gl}(E_{X})/\mathfrak{g}_{X}$$

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### Example 1: 1-structures

Let *E* be a *trivial* vector bundle over *M* and let  $s : M \to FR(E)$  be a smooth global frame.
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 $\mathfrak{I}_{X}^{P}$  coincides with the Christoffel tensor  $\Gamma_{X}: T_{X}M \to \mathfrak{gl}(E_{X})$ .

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 $\mathfrak{I}_{X}^{P}$  coincides with the Christoffel tensor  $\Gamma_{X}$  :  $T_{X}M \to \mathfrak{gl}(E_{X})$ .

#### Lemma

 $\mathfrak{I}_x^P = 0$  iff  $\nabla$  is flat.

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 $\pi: E \rightarrow M$  vector bundle with a Riemannian metric g

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 $\pi: E \to M$  vector bundle with a Riemannian metric g $\nabla$  connection on E.

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O(k)-structure of *g*-orthonormal frames of *E*:  $P \subset FR(E)$ 

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$$\Im_{X}^{P}(\nu) = \frac{1}{2} \big( \Gamma(\nu) + \Gamma(\nu)^{*} \big) = -\frac{1}{2} \nabla_{\nu} g \in \operatorname{sym}(E_{X})$$

for all  $x \in M$ ,  $v \in T_x M$ .

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for all  $x \in M$ ,  $v \in T_x M$ .

Lemma

 $\mathfrak{I}_{x}^{P} = 0$  iff g is  $\nabla$ -parallel.

Example 3:  $O(k_1) \times O(k_2)$ -structures  $\pi : E \to M$  vector bundle with a Riemannian metric *g* 

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Example 3:  $O(k_1) \times O(k_2)$ -structures  $\pi : E \to M$  vector bundle with a Riemannian metric g $F \subset E$  vector subbundle

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*P* set of frames *adapted* to the orthogonal sum  $E = F \oplus F^{\perp}$  is a *G*-structure on *E*, where  $G = O(k_1) \times O(k_2)$ .

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 $\pi: E \rightarrow M$  vector bundle with a Riemannian metric g

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$$\mathfrak{gl}(E_{\chi})/\mathfrak{g}_{\chi} \cong \operatorname{sym}(E_{\chi}) \oplus \operatorname{Lin}(F_{\chi}, F_{\chi}^{\perp})$$
$$T + \mathfrak{g}_{\chi} \longmapsto \left(\frac{1}{2}(T + T^{*}), \frac{1}{2}\mathfrak{q}_{\chi} \circ (T - T^{*})|_{F_{\chi}}\right)$$

 $\mathfrak{I}_{X}^{P}(\mathbf{v}) = \left(-\frac{1}{2}\nabla_{\mathbf{v}}\boldsymbol{g}, \alpha_{\mathbf{x}}(\mathbf{v}, \cdot) + \frac{1}{2}\mathfrak{q} \circ \nabla_{\mathbf{v}}\boldsymbol{g}|_{F_{\mathbf{x}}}\right)$ 

 $\mathfrak{q}: \mathbf{E} \to \mathbf{F}^{\perp}$  projection,  $\alpha$  is the 2nd fundamental form of  $\mathbf{F}$ .

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 $\mathfrak{q}: E \to F^{\perp}$  projection,  $\alpha$  is the 2nd fundamental form of F.

#### Lemma

 $\mathfrak{I}_{x}^{P} = 0$  iff g is  $\nabla$ -parallel and F is parallel (i.e., covariant derivative of sections of F are in F).

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Example 4: O(k - 1)-structures *E* vector bundle with Riemannian metric *g* 

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Example 4: O(k - 1)-structures *E* vector bundle with Riemannian metric *g*  $\epsilon$  smooth section of *E*, with  $g(\epsilon, \epsilon) = 1$ 

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*E* vector bundle with Riemannian metric *g*  $\epsilon$  smooth section of *E*, with  $g(\epsilon, \epsilon) = 1$ 

 $P \subset FR(E)$  set of orthonormal frames of *E* whose first element is  $\epsilon$  is a *G*-structure on *E*, where:

$$G = \begin{pmatrix} 1 & 0 \\ 0 & \mathrm{O}(k-1) \end{pmatrix}$$

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$$\mathfrak{I}_X^P(\nu) = \left(-\frac{1}{2}\nabla g, \nabla_\nu \epsilon + \frac{1}{2}(\nabla_\nu g)\epsilon\right)$$

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*E* vector bundle with Riemannian metric *g*  $\epsilon$  smooth section of *E*, with  $g(\epsilon, \epsilon) = 1$ 

 $P \subset FR(E)$  set of orthonormal frames of *E* whose first element is  $\epsilon$  is a *G*-structure on *E*, where:

$$G = \begin{pmatrix} 1 & 0 \\ 0 & \mathrm{O}(k-1) \end{pmatrix}$$

 $G_x$  is the set of isometries of  $E_x$  that fix  $\epsilon(x)$ ,  $\mathfrak{g}_x$  is the set of endomorphisms T of  $E_x$  such that  $T(\epsilon(x)) = 0$ .

$$\mathfrak{gl}(E_x)/\mathfrak{g}_x \cong \operatorname{sym}(E_x) \oplus \epsilon(x)^{\perp}$$
$$T + \mathfrak{g}_x \longmapsto \left(\frac{1}{2}(T + T^*), \frac{1}{2}(T - T^*) \cdot \epsilon(x)\right)$$
$$\mathfrak{I}_x^P(v) = \left(-\frac{1}{2}\nabla g, \nabla_v \epsilon + \frac{1}{2}(\nabla_v g)\epsilon\right)$$

#### Lemma

$$\mathfrak{I}_{x}^{P} = \mathsf{0}$$
 iff g is  $abla$ -parallel and  $abla \epsilon = \mathsf{0}$ .

Paolo Piccione (IME–USP)

G-structures and affine immersions

Example 5: U(*I*)-structures k = 2I, *E* vector bundle with a Riemannian metric *g* and an almost complex anti-symmetric structure *J*.

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 $\mathfrak{gl}(E_{\chi})/\mathfrak{g}_{\chi} \cong \operatorname{sym}(E_{\chi}) \oplus \overline{\operatorname{Lin}}_{a}(E_{\chi})$  $T + \mathfrak{g}_{\chi} \longmapsto \left(\frac{1}{2}(T + T^{*}), \frac{1}{2}[T - T^{*}, J_{\chi}]\right)$ 

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# Outline

### G-structures

- 2 Principal spaces
- 3 Principal fiber bundles
- 4 Connections
- Inner torsion of a G-structure

### Infinitesimally homogeneous affine manifolds with G-structure

#### Immersion theorems

Paolo Piccione (IME–USP)

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Infinitesimally homogeneous manifolds  $(M, \nabla)$  affine manifold,

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#### Definition

 $(M, \nabla, P)$  is *infinitesimally homegeneous* if  $\mathfrak{I}^P$ , *T* and *R* are *constant* in frames of the *G*-structure *P*.

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 $(M, \nabla, P)$  is *locally homogeneous* if for all  $x, y \in M$  and every *G*-structure preserving map  $\sigma : T_x M \to T_y M$  there exists neighborhoods  $U \ni x, V \ni y$  and a smooth *G*-structure preserving affine diffeomorphism  $f : U \to V$  with f(x) = y and  $df_x = \sigma$ .

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#### Theorem

 $(M, \nabla, P)$  infinitesimally homogeneous  $\implies (M, \nabla, P)$  locally homogeneous. If  $(M, \nabla)$  is geodesically complete and M is simply connected, then  $(M, \nabla, P)$  is globally homogeneous.

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#### Proof.

An application of the Cartan–Ambrose–Hicks theorem!

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- $(M_i, g_i)$  Riemannian,  $i = 1, 2, M = M_1 \times M_2$  endowed with the product metric  $g, \nabla$  Levi–Civita connection of g, P the  $O(n_1) \times O(n_2)$ -structure given by the orthonormal frames *adapted* to the product. Then,  $(M, \nabla, P)$  is infinitesimally homogeneous iff  $(M_i, g_i)$  has constant sectional curvature, i = 1, 2.

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 More generally, product of infinitesimally homogeneous manifolds is infinitesimally homogeneous.

Paolo Piccione (IME–USP)

(M, g) 3-dimensional homogeneous manifold with 4-dim. isometry group (includes: Berger spheres, Heisenberg space Nil<sub>3</sub>,  $\widetilde{PSL_2(\mathbb{R})}$ , products  $\mathbb{S}^2 \times \mathbb{R}$ ,  $\mathbb{H}^2 \times \mathbb{R}$ )

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*R* computed explicitly: formula involving only  $g \in \xi$ 

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# Outline

### 1 G-structures

- 2 Principal spaces
- 3 Principal fiber bundles
- 4 Connections
- 5 Inner torsion of a *G*-structure
- Infinitesimally homogeneous affine manifolds with G-structure

### 7 Immersion theorems

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- $\widehat{\nabla}$  a connection on  $\widehat{E} = TM \oplus E$

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### Definition

An *affine immersion* of  $(M, E, \widehat{\nabla})$  into  $(\overline{M}, \overline{\nabla})$  is a pair (f, L), where  $f: M \to \overline{M}$  is a smooth map,  $L: \widehat{E} \to f^*T\overline{M}$  is a connection preserving vector bundle isomorphism with:  $L_x|_{T_xM} = df_x, \quad \forall x \in M.$ 

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### Lemma (Uniqueness)

If *M* is connected, given  $(f^1, L^1)$  and  $(f^2, L^2)$  with  $f^1(x_0) = f^2(x_0)$  and  $L^1(x_0) = L^2(x_0)$ , then  $(f^1, L^1) = (f^2, L^2)$ .

Theorem (part 1)

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  = n + k;
- $\widehat{P} \subset \operatorname{FR}(\widehat{E})$  a G-structure on  $\widehat{E}$ .

Theorem (part 2)

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Assume that for all  $x \in M$ ,  $y \in \overline{M}$  and  $\sigma : \widehat{E}_x \to T_y \overline{M}$  G-structure preserving:

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Then, for all  $x_0 \in M$ ,  $y_0 \in M$ ,  $\sigma_0 : \widehat{E}_x \to T_{y_0}\overline{M}$  G-structure preserving, there exist a locally defined affine immersion (f, L) of  $(M, E, \nabla)$  into  $(\overline{M}, \overline{\nabla})$  with  $f(x_0) = y_0$ ,  $L(x_0) = \sigma_0$ , and such that L is G-structure preserving.

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If *M* is simply connected and  $(\overline{M}, \overline{\nabla})$  is geodesically complete, then the affine immersion is global.

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### Applications: isometric immersion theorem into:

- space forms,
- Kähler manifolds with constant holomorphic curvature,
- all homogeneous geometries in dimension 3,
- Lie groups,
- products, etc.